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INFLUENCE OF WIND DIRECTION ON THE SURFACE ROUGHNESS OF VINEYARDS

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1 ABSTRACT

2 Remote sensing-based models are the most viable means of collecting the high-resolution
3 spatially distributed estimates of evaporative water loss needed to manage irrigation and ensure
4 the effective use of limited water resources. However, due to the unique canopy structure and
5 configuration of vineyards, these models may not be able to adequately describe the physical
6 processes driving evapotranspiration from vineyards. Using data collected from 2014 to 2016 as
7 a part of the Grape Remote sensing Atmospheric Profile and Evapotranspiration Experiment
8 (GRAPEX), the twofold objective of this study was to *i.* identify the relationship between the
9 roughness parameters, zero-plane displacement height (d_o) and roughness length for momentum
10 (z_o), and local environmental conditions, specifically wind direction and vegetation density and
11 *ii.* determine the effect of using these relationships on the ability of the remote sensing-based
12 Two-Source Energy Balance (TSEB) model to estimate the sensible (H) and latent (λE) heat
13 fluxes. Although little variation in d_o was identified during the growing season, a well-defined
14 sigmoidal relationship was observed between z_o and wind direction. When the output from a
15 version of the TSEB model incorporating these relationships (TSEB_{VIN}) was compared to output
16 from the standard model (TSEB_{STD}), there were large changes to the roughness parameters,
17 particularly z_o , but only modest changes in the turbulent fluxes. When the output from TSEB_{VIN}

18 was compared to that of a version using a parameterization scheme representing open canopies
19 (TSEB_{OPN}), the mean absolute difference between the estimates of d_o and z_o were 0.44 m and
20 0.25 m, respectively. While these values represent differences in excess of 45%, the turbulent
21 fluxes differed by just 13 W m⁻² or 10%, on average. The results suggest that the TSEB model is
22 largely insensitive to changes in the roughness parameters. This also suggests that the
23 requirement for highly accurate roughness values has limited utility in the application of the
24 TSEB model in vineyard systems. Since there is no significant advantage to using the more
25 complex TSEB_{OPN} and TSEB_{VIN} models, it is recommended that the standard model be used.

26 **INTRODUCTION**

27 In terms of both quantity and value, California is among the largest wine producing
28 regions in the world. According to statistics compiled by the US Department of the Treasury
29 (2017), California’s average wine production during the last decade approaches 2.41 GL (638
30 million gallons) of wine annually; this is nearly 90% of all US production. As a result, the
31 California wine industry contributes nearly \$60B to the state’s economy and \$115B to the US
32 economy each year according to industry analyses (MKF Research, 2007; John Dunham and
33 Associates, 2016). In turn, the wine industry is dependent on the state’s wine grape growers.
34 There are approximately 250,000 ha of wine grape vineyards in California producing 363 Gg of
35 fruit valued at more than \$3B each year (California Department of Food and Agriculture, 2017).

36 Since California, like many other wine-producing regions, is characterized by limited
37 rainfall and high evaporative demand during the growing season, irrigation is critical to ensure
38 vineyard productivity. However, the timing and amount of water available can significantly
39 impact the vine vigor, crop yield, and fruit quality (Chapman et al. 2005; Chaves et al. 2007;
40 Webb et al. 2007). For example, while adequate moisture is needed early in the growing season
41 from bud burst to fruit set to ensure crop yield, moderate water stress is preferred later in the
42 growing season to enhance fruit quality (Lobell et al. 2007; Zarrouk et al. 2012). Therefore,
43 careful irrigation management is of paramount importance to wine grape production (Ojeda et al.
44 2002; Pellegrino et al. 2005; Acevedo-Opazo et al. 2010; Bellvert et al. 2015). Moreover, the
45 factors influencing water availability, water loss via evapotranspiration, and crop water stress are
46 numerous and vary both spatially and temporally. Thus, as discussed by Arno et al. (2009),
47 Campos et al. (2010), and Pagay (2016), among others, precision methods for scheduling
48 irrigation at a sub-vineyard scale are needed so that both the timing and amount of water applied
49 to the vines is appropriate to their individual needs.

50 Remote sensing-based approaches are the most viable means to monitor the within-field
51 variability in water loss and vine water stress needed for irrigation management decisions
52 (Baluja et al. 2012; Semmens et al. 2016; Xia et al. 2016). However, remote sensing-based
53 models also have limitations. One of these limitations is the simple empirical relations that are
54 typically used to determine the parameters that describe the aerodynamic roughness of the
55 surface which are used not only to calculate the wind profiles but also the resistance terms
56 needed to calculate the fluxes of heat and moisture. For instance, the thermal remote sensing-
57 based two-source energy balance model (TSEB; Norman et al.1995; Kustas and Norman1997,
58 1999, 2000), and the closely related ALEXI/DisALEXI modeling system (Anderson et al., 1997,
59 2004, 2007), determine two key roughness parameters, namely the zero-plane displacement
60 height (d_o ; referred to as displacement height hereafter) and roughness length for momentum (z_o ;
61 referred to as roughness length hereafter) as a fraction of vegetation height following the well-
62 known relationships given by Norman and Campbell (1980).

63 The surface roughness parameters, d_o and z_o , describe the effect exerted by the surface on
64 near-surface wind flow due to drag. They are often defined in terms of Monin-Obukhov
65 Similarity Theory and the vertical profile of horizontal wind speed (Brutsaert 1982; Arya 2001).
66 In this framework, z_o is defined as the height above the lower boundary of the logarithmic profile
67 where the horizontal wind speed goes to zero. Depending on the size and density of the
68 roughness elements, the position of the lower boundary lies somewhere between the base and top
69 of the roughness elements. As the name implies, the d_o accounts for the height of the lower
70 boundary of the profile above the land surface. However, these quantities can also be defined in
71 terms of momentum transfer. In this context, z_o characterizes the efficiency of momentum

72 transport to the surface (Shaw and Pereira 1982) while d_o indicates the mean height of
73 momentum transfer to the surface (Raupach 1992, 1994; Brunett et al. 1994)

74 The commonly-used relationships between d_o , z_o and vegetation height, such as those
75 used by TSEB and ALEXI/DisALEXI, neglect numerous other factors including the spacing,
76 geometry, and frontal area that impact surface roughness by assuming dense closed canopy. (See
77 Brutsaert (1982) for a concise discussion of the evolution of these empirical relationships.) In
78 contrast, d_o and z_o for sparse or open canopies are also influenced by the organizational structure
79 of the canopy, i.e. the density and distribution of biomass (Shaw and Pereira 1982; Raupach
80 1992, 1994; Verhoef et al. 1997). As discussed by Zeng and Wang (2007), failing to account for
81 the factors beyond canopy height that can affect surface roughness, significant errors of up to
82 50% can be introduced into the estimates of d_o and z_o . Other studies, such as Pitman (1994) and
83 Maurer et al. (2013, 2015) have shown errors in d_o and z_o can result in significant errors in
84 modeled fluxes of momentum, heat, and moisture.

85 Although the exact configuration varies from vineyard-to-vineyard, vineyards are
86 generally characterized by trellised vines that are between 1 m and 2.5 m in height and separated
87 by a broad inter-row space on the order of 3 m wide. Due to this design, it is likely that d_o and z_o
88 are influenced other factors beyond vine height. Although studies are limited, past research also
89 suggests d_o and z_o are impacted by wind direction and vegetation density. The observational
90 studies of Hicks (1973) and Riou et al. (1987) suggests surface roughness varies with wind
91 direction while the work of Sene (1994) suggests that the surface roughness increases with
92 increasing vine density. These results are further supported by the work of Weiss and Allen
93 (1976), who found that turbulent intensity was greater when the wind flow was perpendicular to
94 the vine rows as opposed to parallel to them, and Padro et al. (1994), who found that the

95 aerodynamic resistance over a vineyard changed as a function of wind direction. Most recently,
96 the large eddy simulation (LES) studies of Chahine et al. (2014) indicates that both d_o and z_o vary
97 with wind direction with the lowest z_o and largest d_o occurring when winds are parallel to the
98 rows.

99 Building on these earlier studies, the objective of this study was twofold. The first aim
100 was to identify a functional relationship between each of the roughness parameters, d_o and z_o ,
101 and both wind direction and vegetation density as expressed in terms of leaf area index (LAI).
102 The second objective was to evaluate the impact of allowing the roughness parameters to vary
103 dynamically in response to changing environmental conditions on the surface fluxes computed
104 by the TSEB model. The following section provides a description of field site, datasets, remote
105 sensing-based ET model, and analysis techniques. The third section discusses the results of this
106 study. Finally, the last section includes the conclusions and recommendations that can be drawn
107 from this work.

108 **MATERIALS AND METHODS**

109 Site Description

110 As can be seen in Figure 1, the study was conducted as a part of the Grape Remote
111 sensing Atmospheric Profile and Evapotranspiration eXperiment (GRAPEX) over a pair of
112 adjacent vineyards located near the city of Lodi in California's Central Valley, USA (38.29 N
113 121.12 W). This region is characterized by warm, dry conditions and an evaporative demand
114 ranging from 889 to 1270 mm of water during the growing season, which is defined here as April
115 through August (Semmens et al. 2015). Also, the air temperature averages near 22°C and the
116 total precipitation is typically 24 mm during the same period.

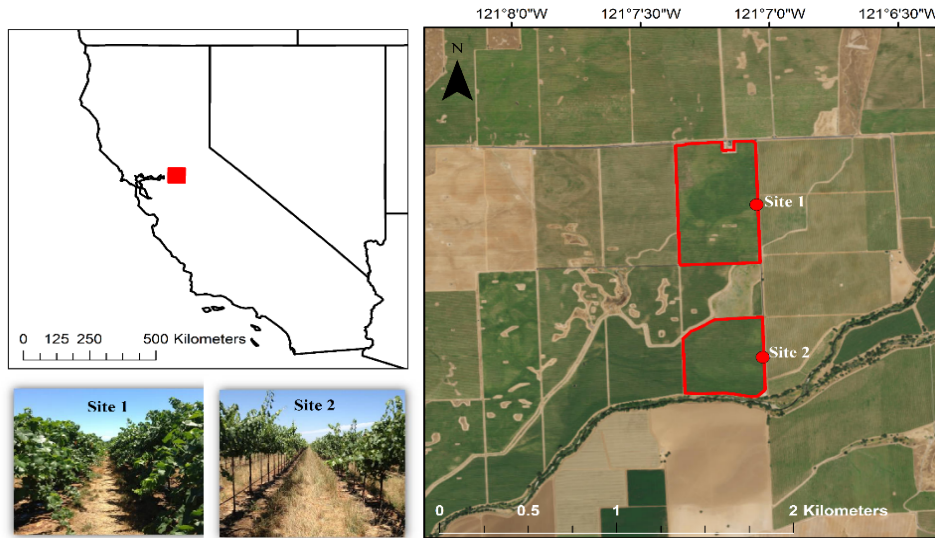


Figure 1 The location of study area is shown. The northern (Site 1) and southern (Site 2) vineyards are outlined in red while the location of the micrometeorological towers are represented by the red dots. The photo of the two vineyards were taken on August 6th, 2013.

117 Both vineyards are planted with Pinot Noir vines and share similar trellis structure and
 118 vine management. The main shoots of the vines, which are planted every 1.52 m along the east-
 119 west running trellising system, are attached to the quadrilateral cordon trellis at a height of 1.45
 120 m. Although the height of the vines ranges between 2.0 and 2.5 m, the plant biomass is
 121 concentrated in the upper third of the canopy. The rows are oriented east-west with an inter-row
 122 spacing between the trellises is 3.35 m. This inter-row space is planted with a grass cover crop to
 123 regulate soil moisture early in the growing season following the winter season when this region
 124 receives virtually all of its rainfall. The cover crop enters senescence in mid-March and is mowed
 125 in late April or early May. As a result, the cover crop is inactive during the period considered in
 126 this study.

127 Other management practices shared by the two vineyards include the timing and amount
 128 of drip irrigation, pruning activities, and application of agrochemicals.

129 The primary difference between the two vineyards is the age of the vines. The vines at
130 the northern vineyard (Site 1) were more mature having been planted in 2005 while the southern
131 vineyard (Site 2) was planted in 2009. The northern vineyard, which has an area of 35 ha, is also
132 somewhat larger than the southern vineyard; the latter has an area of 21 ha.

133 Data Collection and Post-Processing

134 The measurements of near-surface wind profiles, surface fluxes, meteorological
135 conditions used in this study were collected using identical instrument packages. The wind
136 velocity profiles were collected using four sonic anemometers (CSAT3¹, Campbell Scientific,
137 Logan, Utah) mounted facing due west (270°) at 2.5 m, 3.75 m, 5 m and 8.0 m agl, respectively.
138 The turbulent energy fluxes were determined via the eddy covariance method using a sonic
139 anemometer (CSAT3, Campbell Scientific, Logan, Utah) to measure the orthogonal wind
140 velocity components and an infrared gas analyzer (EC-150, Campbell Scientific) to measure the
141 water vapor and carbon dioxide concentrations. Both sensors were mounted at 5 m agl facing due
142 west and operated using a sampling frequency of 20 Hz. The net radiation was determined from
143 measurements collected via a four-component radiometer (CNR-1, Kipp and Zonen, Delft,
144 Netherlands) mounted 6 m agl. The soil heat flux was calculated as the average of 5 heat flux
145 plates (HFT-3, Radiation Energy Balance Systems, Bellevue, Washington) deployed at a depth 8
146 cm along a diagonal transect across the inter-row space. A pair of thermocouples, which were
147 buried at depths of 2 cm and 6 cm, and a soil moisture sensor (HydraProbe, Stevens Water
148 Monitoring System, Portland, Oregon), which was buried at a depth of 5 cm, was co-located with
149 each heat flux plate. Additional auxiliary measurements were collected using a combined

¹ The use of trade, firm, or corporation names in this article is for the information and convenience of the reader. Such use does not constitute official endorsement or approval by the US Department of Agriculture or the Agricultural Research Service of any product or service to the exclusion of others that may be suitable

150 humidity and temperature sensor (HMP45C, Vaisala, Helsinki, Finland) mounted 5 m agl, two
151 thermal infrared thermometers (SI-111, Campbell Scientific) mounted 2.5 m agl at a 45° to the
152 surface, and a tipping bucket rain gauge (TE525, Texas Electronics, Dallas, Texas),

153 The high-frequency (20 Hz) wind velocity data collected as a part of the wind profiles
154 were post-processed by first screening the raw data to identify and remove without replacement
155 nonphysical values and data spikes following the method of Goring and Nikora (2002). Then, the
156 coordinate system of the wind velocity components was rotated to align with prevailing wind
157 direction (Tanner and Thurtell, 1969; Kaimal and Finnigan, 1994). Finally, the hourly mean
158 wind speed and direction was calculated.

159 Similarly, the flux data were post-processed using the full suite of standard corrections
160 and adjustments. Nonphysical values and data spikes were removed without replacement from
161 the high frequency data and a two-dimensional coordinate rotation was applied to the wind
162 velocity data following the same procedures as used with the wind profiles. Also, the sonic
163 temperature was converted to air temperature by adjusting for humidity effects following the
164 approach described by Liu et al. (2001). Third, the data were corrected for sensor displacement
165 and frequency response attenuation according to the methods outlined by Massman (2000) and
166 Massman and Lee (2002). Finally, hourly turbulent fluxes were calculated. The moisture and
167 carbon dioxide fluxes were then corrected for the effects of buoyancy and water vapor density
168 (Webb et al., 1980).

169 Leaf Area Index

170 The leaf area index was estimated from satellite imagery for each year during the
171 GRAPEX project using the reference-based technique of Gao et al. (2012). The technique uses
172 the relationship between the LAI of homogenous MODIS pixels (500 m resolution) and the

173 surface reflectance of the corresponding Landsat pixels to develop a regression tree. The
174 resulting regression tree was then applied to the Landsat imagery to generate a LAI map at 30-m
175 spatial resolution. The LAI map was smoothed and gap-filled to generate daily LAI using the
176 Savitzky-Golay filter approach (Jonsson and Eklundh 2004). Since the experimental sites locate
177 in the overlapped area of two adjacent Landsat paths, over 60 clear Landsat 7 and 8 images were
178 acquired each year from 2013 to 2016. The resulting LAI curves agreed with in-situ observation
179 to within 5% to 10%, on average. Details of the procedure and resulting LAI product used in this
180 study are provided in Sun et al (2017).

181 Two-Source Energy Balance Model Description

182 The two-source energy balance model (TSEB), which was originally developed by
183 Norman et al. (1995) and Kustas and Norman (1997, 1999, 2000), uses radiometric surface
184 temperature (T_r) to determine the surface energy fluxes while explicitly considering the separate
185 contributions of the soil and canopy. More specifically, the model uses T_r , meteorological data
186 such as wind speed (U), and vegetation characteristics such as leaf area index (LAI) to
187 simultaneously solve a family of equations describing the energy fluxes from the soil and
188 canopy. Although a detailed description of the model can found elsewhere, e.g. Kustas and
189 Norman (2000) and Kustas et al. (2012), a brief overview is provided here.

190 To begin, TSEB defines the T_r as the area-weighted average of the temperatures of the
191 canopy and soil surface:

$$192 T_r(\phi) = \{f_c(\phi)T_c^4 + [1 - f_c(\phi)]T_s^4\}^{1/4} \quad (1)$$

193 where $T_r(\phi)$ is the radiometric surface temperature as a function of view angle ϕ , $f_c(\phi)$ is the
194 fractional vegetation cover as a function of ϕ , T_c is the canopy temperature, and T_s is the soil
195 surface temperature. The fractional vegetation cover is derived from LAI according to:

196 $f_c(\phi) = 1 - \text{EXP}\left(-\frac{\Omega \text{LAI}}{2 \cos \phi}\right)$ (2)

197 where Ω is a dimensionless clumping index, which indicates the degree heterogeneity in the
 198 spatial distribution of the leaf area (Anderson et al., 2005) and the other terms are defined above.

199 Additionally, TSEB defines the energy budgets of the soil surface and canopy,
 200 respectively, as follows:

201 $R_{Ns} = H_s + \lambda E_s + G$ (3a)

202 $R_{Nc} = H_c + \lambda E_c$ (3b)

203 where R_N is the net radiation, H is the sensible heat flux, and λE is the latent heat flux. The
 204 subscript s refers to the soil surface while the subscript c refers the canopy.

205 The net radiation for the soil and canopy are determined using a simplified radiation
 206 transfer model (Kustas and Norman 2000) while G is computed following a modification of the
 207 method described by Santanello and Friedl (2003). Rather than using the sinusoidal function
 208 given by Santanello and Friedl (2003) to describe the relationship between G and R_n over time, a
 209 double asymmetric sigmoid function was used because it better fit the observed relationship at
 210 the study site (Nieto et al., this issue, a). That work showed the ratio of G to R_n varied from a
 211 minimum of -0.5 near sunrise/sunset to maximum near 0.35 at mid-day.

212 For the soil surface and canopy, respectively, H is calculated according to:

213 $H_s = \rho C_p \frac{T_s - T_{ac}}{r_s}$ (4a)

214 $H_c = \rho C_p \frac{T_c - T_{ac}}{r_x}$ (4b)

215 where ρ is the air density, C_p is the specific heat of air, T_{ac} is the within-canopy air temperature,
 216 r_s is the resistance of the soil surface to heat exchange, r_x is the resistance of the total canopy to

217 heat exchange, and the other terms are defined above. In turn, λE_s is calculated as a residual
 218 while λE_c is calculated according to:

$$219 \quad \lambda E_c = \alpha f_c \frac{\Delta}{\Delta + \gamma} R_{Nc} \quad (5)$$

220 where α is the Priestley-Taylor coefficient (Priestley and Taylor 1972) which has an initial value
 221 of 1.26, Δ is the slope of the saturation vapor pressure-temperature curve, γ is the psychrometric
 222 constant, and the other terms are defined above.

223 The resistance of the soil surface to heat exchange (r_s) was estimated based on a modified
 224 form of the empirical approach of Sauer et al. (1995) developed by Kustas and Norman (2000):

$$225 \quad r_s = [a(T_s - T_{ac})^{1/3} + bU_s]^{-1} \quad (6)$$

226 where both a ($0.0025 \text{ m K}^{-1} \text{ s}^{-1}$) and b (0.012) are constants, U_s is the wind speed just above the
 227 soil surface where the effects of soil roughness is minimal, and the other terms are defined
 228 above. In turn, U_s is calculated according to Goudriann (1977):

$$229 \quad U_s = U_c \text{EXP} \left[-0.28 \sqrt[3]{\frac{\text{LAI}^2 h_c}{\ell}} \left(1 - \frac{1}{20h_c} \right) \right] \quad (7)$$

230 where U_c is the wind speed at the top of the canopy, h_c is the canopy height, ℓ is the mean leaf
 231 size, and the other terms are defined above. Similarly, U_c calculated according to Goudriann
 232 (1977) as follows:

$$233 \quad U_c = U \left[\frac{\ln\left(\frac{h_c - d_o}{z_o}\right)}{\ln\left(\frac{z - d_o}{z_o}\right) - \Psi} \right] \quad (8)$$

234 where U is the wind speed at height z above the canopy, d_o is the displacement height, z_o is the
 235 roughness length for momentum, Ψ is the correction for atmospheric stability, and the other
 236 terms are defined above. Finally, as described by Norman et al. (1995), r_x is defined as:

$$237 \quad r_x = \frac{c\sqrt{\ell/U_d}}{\text{LAI}} \quad (9)$$

238 where c ($90 \text{ s}^{1/2} \text{ m}^{-1}$) is a constant and U_d is determined analogously to U_s as:

$$239 \quad U_d = U_c \text{EXP} \left[-0.28 \sqrt[3]{\frac{\text{LAI}^2 h_c}{\ell}} \left(1 - \frac{z_o + d_o}{h_c} \right) \right] \quad (10)$$

240 and the other terms are defined above.

241 For the standard version of the TSEB model (TSEB_{STD}), the roughness parameters, d_o
242 and z_o are estimated using the well-known empirical functions of h_c given by Norman and
243 Campbell (1980), among others:

$$244 \quad d_o = \frac{2}{3} h_c \quad (11a)$$

$$245 \quad z_o = \frac{h_c}{8} \quad (11b)$$

246 For this study, h_c of the vineyard that was used by the TSEB model was estimated as a function
247 of LAI (see Nieto et al., this issue, b). Using a typical vines height of 2.25 m for the GRAPEX
248 field sites, these relationships estimate d_o and z_o as 1.50 m and 0.28 m, respectively.

249 Numerous studies, such as Shaw and Pereira (1982), has demonstrated that the roughness
250 length is influenced by other factors beyond h_c ; this is particularly true of sparse open canopies.
251 Thus, due to the configurations of vineyards, the standard approach for estimating the roughness
252 parameters may not be the most appropriate. Therefore, an alternate version of the TSEB model
253 (TSEB_{OPN}) was also used in this study. This version of the model uses the approach of Schaudt
254 and Dickinson (2000) to estimate the roughness parameters. The approach builds on the earlier
255 work of Raupach (1992) and Lindroth (1993) to consider canopy shape and density, in addition
256 to h_c , when estimating d_o and z_o .

257 The method of Schaudt and Dickinson (2000) begins with the assumption that the
258 vegetation height of woody vegetation changes little over time. Instead, the roughness changes in
259 response to changes in vegetation density, i.e. LAI, and the frontal area of the vegetation. The

260 frontal area is the projected area of the canopy perpendicular to the wind direction of that
 261 intercept and interacts with the air flow; it is a function of the canopy height, width, and shape
 262 (Raupach 1992, 1994). From this Raupach (1994) proposed the frontal leaf area index (λ_c)
 263 defined as:

$$264 \quad \lambda_c = f_c \frac{h_c}{w_c} \quad (12)$$

265 where f_c is the fractional canopy cover, w_c is the canopy width, and the other terms are defined as
 266 above. He further proposed the following relations for d_o and z_o as a function of λ_c :

$$267 \quad d_o = h_c \left[1 - \frac{1 - e^{-(a\lambda_c)^{1/2}}}{(a\lambda_c)^{1/2}} \right] \quad (13a)$$

$$268 \quad z_o = \begin{cases} h_c [b_1 \lambda_c^{c_1} e^{-d\lambda_c^{e_1}} + f_1] & \lambda_c \leq 0.152 \\ h_c [b_2 \lambda_c^{c_2} (1 - e^{-d\lambda_c^{e_2}}) + f_2] & \lambda_c > 0.152 \end{cases} \quad (13b)$$

269 where a (15.0), b_1 (5.86), b_2 (0.0537), c_1 (1.33), c_2 (-0.51), d (10.9), e_1 (1.12), e_2 (0.874),
 270 f_1 (8.6×10^{-4}), and f_2 (3.68×10^{-3}) are coefficients and the other terms are defined as above.

271 Finally, using the Schaudt and Dickinson (2000) approach, the roughness parameters used by the
 272 model are calculated as the product of these initial estimates and a correction factor. The
 273 correction factor for d_o and z_o , respectively, are:

$$274 \quad f_d = 1 - ae^{-bLAI} \quad (14a)$$

$$275 \quad f_z = \begin{cases} c_1 LAI^{3/2} + d_1 & LAI \leq 0.8875 \\ c_2 e^{-d_2 LAI} + 1 & LAI > 0.8875 \end{cases} \quad (14b)$$

276 where a (0.3991), b (-0.1779), c_1 (0.3299), c_2 (1.6771), d_1 (2.1713), and d_2 (0.1717) are
 277 coefficients and the other terms are defined as above.

278 Finally, a version of the TSEB model (TSEB_{VIN}) that uses the relationships developed by
279 this study was also used herein to evaluate the impact of the roughness parameterization on the
280 modeled fluxes.

281 Calculation of Roughness Parameters

282 Using the data collected during the 2014 to 2016 growing seasons as a part of the
283 GRAPEX project, d_o and z_o were calculated assuming a logarithmic wind profile and neutral
284 atmospheric stability conditions. Under these conditions, the wind speed can be expressed as a
285 function of height:

$$286 \quad U = \frac{u_*}{k} \ln \left(\frac{z-d_o}{z_o} \right) \quad (15)$$

287 where u_* is the friction velocity, k is the von karmann constant, and the other terms are defined
288 above (Stull, 1988; Arya, 2001). Based on this relation, the d_o can be determined using paired
289 measurements of wind speed taken at two different heights as follows:

$$290 \quad d_o = z_1 - \frac{\Delta z}{e^{k\Delta U/u_*} - 1} \quad (16)$$

291 where z_1 is the lower measurement height, Δz is the separation distance between the two
292 measurements, ΔU is the difference in the measured wind speed, and the other terms are defined
293 above. Once d_o is determined, z_o can be calculated by rearranging Eq. (15):

$$294 \quad z_o = \frac{z-d_o}{e^{kU/u_*}} \quad (17)$$

295 This approach, and particularly the determination of d_o , is highly sensitive to any errors in
296 the measurements and any violations of the underlying assumptions (Brutsaert, 1982). For
297 example, a preliminary sensitivity analysis for the GRAPEX study sites indicates a 5% error in
298 ΔU results in a 5% to 15% error in the calculated d_o , depending on the measurement heights

299 used. Therefore, the data used were restricted to clear-sky days with near-neutral stability and
 300 sufficient turbulent mixing (See Table 1 for a complete listing of constraints).

301 For each vineyard and time period identified as valid, all possible measurement height
 302 combinations – for the purpose of this study, the wind speed measurements from the eddy
 303 covariance system were also included as a part of the profile - were used to estimate d_o following
 304 Eq. (16). As a further quality control step, the six estimates of d_o were compared. If they agreed
 305 to within 10%, d_o during the period was taken as the average of all of the d_o estimates. If there
 306 was disagreement among the estimates of d_o , the period was neglected in the subsequent analysis
 307 of d_o . Due to the constraints placed on the calculation of d_o , there were only a small number of d_o
 308 values obtained for each vineyard each year (see below for additional information). As a result,
 309 the mean d_o value (1.40 m) was used in the subsequent calculation of z_o .

310 The roughness length was calculated in a similar manner. For each vineyard, the valid
 311 periods conforming to the constraints listed in Table 1 were first identified. Then z_o was estimated
 312 for each measurement height in the profile using Eq. (17). Again, as a further quality control
 313 step, the four estimates of z_o for each period were compared and only if they agreed to within
 314 10% was the average used for subsequent analyses.

Table 1 The conditions used to constrain the data used to calculate the displacement height and roughness length are listed.

Condition	Constraint for Displacement Height	Constraint for Roughness Length
Incident Solar Radiation (K_i)	$K_i \geq 100 \text{ W m}^{-2}$	
Wind Speed (U)	$U \geq 1 \text{ m s}^{-1}$	
Wind Direction (φ)	$ \varphi - 270^\circ \leq 90^\circ$	
Friction Velocity (u_*)	$u_* \geq 0.1 \text{ m s}^{-1}$	
Atmospheric Stability (ζ)	$-0.02 \leq \zeta \leq 0.01$	$-0.04 \leq \zeta \leq 0.02$

315 The constraints used for determining the valid periods for calculating z_o are relaxed
 316 somewhat compared to those used for estimating d_o . Specifically, the range of near-neutral
 317 conditions was extended slightly. Calculations of d_o are substantially more sensitive to
 318 departures from neutral conditions than the determination of z_o . By using a u^* (0.31 m s^{-1}) typical
 319 of the sites and the stability corrections given by Paulson (1970) and Dyer (1974), the percent
 320 error of the estimates of the roughness parameters was calculated as a function of atmospheric
 321 stability. To account for the effects of atmospheric stability, Eq. (16) and Eq. 17 were modified
 322 to include the stability correction; respectively, for d_o and z_o , the modified relationships are:

$$323 \quad {}^c d_o = z_1 - \frac{\Delta z}{e^{k\Delta U/u_* + \Delta\psi} - 1} \quad (18a)$$

$$324 \quad {}^c z_o = \frac{z - d_o}{e^{kU/u_* + \psi}} \quad (18b)$$

325 where ${}^c d_o$ and ${}^c z_o$ are the estimates of d_o and z_o under non-neutral conditions, ψ is the stability
 326 correction, and the other terms are defined as above. The percent error is then defined as:

$$327 \quad \epsilon_{pct} = 100 \frac{|{}^n x - {}^c x|}{{}^c x} \quad (19)$$

328 where ϵ_{pct} is the percent error, ${}^n x$ is the estimate of the quantity of interest – either d_o and z_o –
 329 assuming neutral conditions, and ${}^c x$ is the estimate of the quantity of interest calculated according
 330 to Eq. (18).

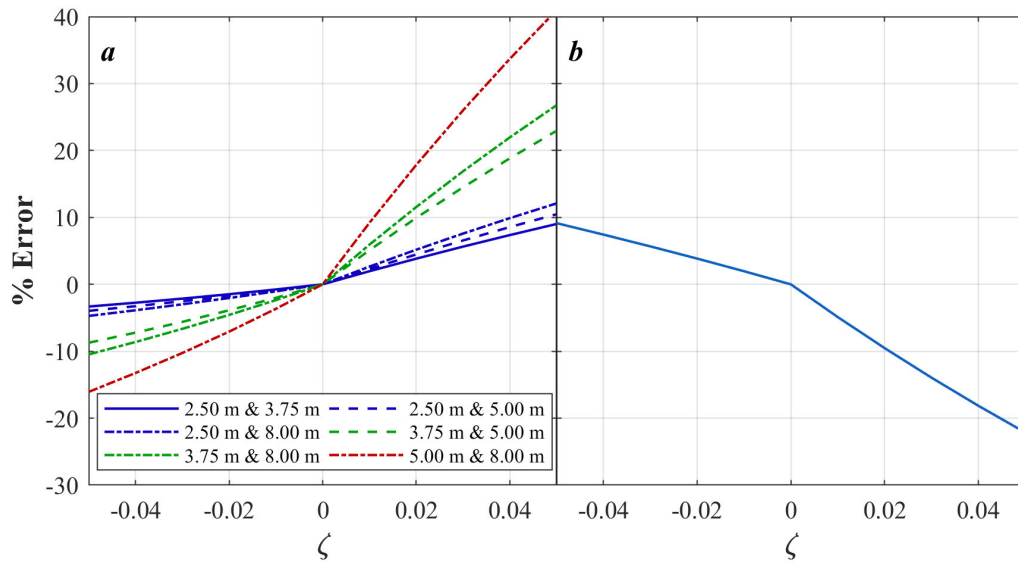


Figure 2 The percent error of the estimates of *a*) displacement height and *b*) roughness length as a function of atmospheric stability.

331 As can be seen in Figure 2, the percent error introduced into the estimates of z_o by non-neutral
 332 conditions is approximately half that introduced into the estimates of d_o . Thus, the range of ζ
 333 allowed when estimating z_o can be extended to -0.04 and 0.02 while introducing less than 10%
 334 error. While the impact of atmospheric stability on the estimates of d_o varies as a function of the
 335 measurement heights used, this is the same maximum error as was allowed for the estimates of
 336 d_o .

337 Statistical Analysis

338 A pair of well-established statistics were used to evaluate the model output of both the
 339 standard and modified TSEB model. The first is the root mean square difference (RMSD) which
 340 is defined as:

$$341 \text{ RMSD} = \sqrt{\frac{1}{n} \sum_{i=1}^n (x_i - y_i)^2} \quad (20)$$

342 where x and y are two estimates of some quantity of interest, n is the number of paired data
343 points, and i is an index. The RMSD can be separated into random and systemic and components
344 according to:

$$345 \text{RMSD}_R = \sqrt{\frac{1}{n} \sum_{i=1}^n (y_i - p_i)^2} \quad (21a)$$

$$346 \text{RMSD}_S = \sqrt{\frac{1}{n} \sum_{i=1}^n (p_i - x_i)^2} \quad (21b)$$

347 where p is the value predicted by ordinary least-squares regression of y against x and the
348 remaining terms are defined above (Willmott 1982; Alfieri et al. 2011).

349 Since the squared difference terms in the RMSD tends to overemphasize the effects of
350 large differences (Legates and McCabe, 1999; Willmott and Matsuura, 2005; Willmott et al.,
351 2012), the mean absolute difference (MAD) was also used. This second metric is defined as:

$$352 \text{MAD} = \frac{1}{n} \sum_{i=1}^n |x_i - y_i| \quad (22)$$

353 where the terms are defined as above. Note that if x and y are the actual (observed) and modeled
354 flux, respectively, then RMSD and MAD, are indicative of the model error. The two metrics are
355 equivalent to the root mean square error (RMSE) and mean absolute error (MAE).

356 **RESULTS AND DISCUSSION**

357 Estimates of the Displacement Height

358 After using the criteria in Table 1 to parse the data collected during the growing seasons
359 from 2014 to 2016 over Vineyard 1, a total of 52 valid periods were identified. During the same
360 timeframe only 10 valid periods were identified at Vineyard 2. While the valid periods identified
361 over the two site differ in terms of wind speed, wind direction, and LAI, they all represent
362 periods when H was near zero and the atmospheric stability was very close to neutral. The
363 difference in the number of near-neutral periods at the two sites is likely due to differences in

364 vegetation density. During the growing season, the LAI of Vineyard 2 was approximately 0.25
 365 $\text{m}^2 \text{m}^{-2}$ or 10% to 25% less than the LAI at Vineyard 1. Because of the lower LAI, the amount of
 366 transpiration is reduced while the surface temperature is increased at Vineyard 2. Both of these
 367 effects act to increase H and, thereby, unstable atmospheric conditions over Vineyard 2. A
 368 comparison of the daytime H and atmospheric stability (ζ) collected at each vineyard during the
 369 growing season further supports this hypothesis. Over the 4 years of GRAPEX, the daytime H at
 370 Vineyard 2 averaged 144 W m^{-2} or approximately 30 W m^{-2} greater than the mean at Vineyard 1.
 371 Similarly, for the same timeframe, ζ , which is the ratio of measurement height to Obukhov
 372 length, was 0.09 lower at Vineyard 2 compared to Vineyard 1.

373 It was not possible to determine the relationship between d_o and site characteristics, such
 374 as LAI, because only a limited range of environmental conditions are represented by the data due
 375 to the small number of valid periods, along with their tendency to be clustered in time. As an

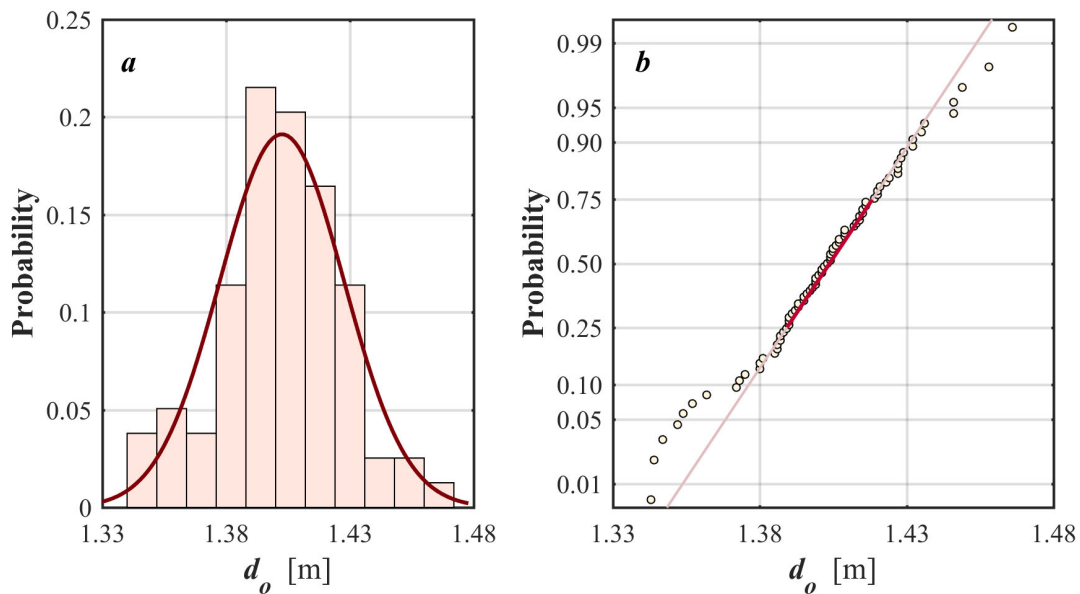


Figure 3 The a) histogram overlaid with corresponding probability density function and b) probability plot for the pooled estimates of the displacement height show that the quantity is normally distributed.

376 example of the clustering, half of the valid periods identified at Vineyard 1 during 2015 occurred
377 on either 9 or 10-June. However, by pooling the data over both sites and all years, it was found
378 that the estimates of d_o calculated for the valid periods, which ranged between 1.34 m and 1.47
379 m, were normally distributed and averaged 1.40 m with a standard deviation of 0.03 m (Fig.3).
380 The mean d_o estimate is very near the center of the vine biomass which is approximately 1.45 m,
381 the height where the vines are attached to the trellis. This agrees with the definition of d_o as the
382 mean height of momentum absorption by a rough surface (Raupach 1992, 1994). The mean value
383 of d_o was used for both the calculation of z_o and the model simulations.

384 Estimates of the Roughness Length

385 After relaxing the constraints, between 36 and 40 valid periods were identified each year
386 at Vineyard 1 while between 8 and 28 valid periods were identified for Vineyard 2 (Table 2). To
387 investigate the relationship between z_o and LAI, the data from each year at Vineyard 1 was bin-
388 averaged based on the corresponding LAI. The same was done for the data collected at Vineyard
389 2 for 2014 and 2016, the 2 years when sufficient valid periods were identified at this site.
390 However, no relationship was evident. This is likely due to relatively small range of LAI
391 represented by the periods identified as valid. An example using the data collect at Vineyard 1
392 during 2015 is shown in Figure 4 represented by the periods identified as valid. An example using
393 the data collect at Vineyard 1 during 2015 is shown in Figure 4.

Table 2 Summary statistics for roughness length for each study site and year.

Statistic	Year		
	2014	2015	2016
<i>Vineyard 1</i>			
n	40	34	40
Mean	0.244	0.242	0.237
Standard Deviation	0.067	0.042	0.065
<i>Vineyard 2</i>			
n	26	8	28
Mean	0.226	0.183	0.232
Standard Deviation	0.049	0.041	0.056

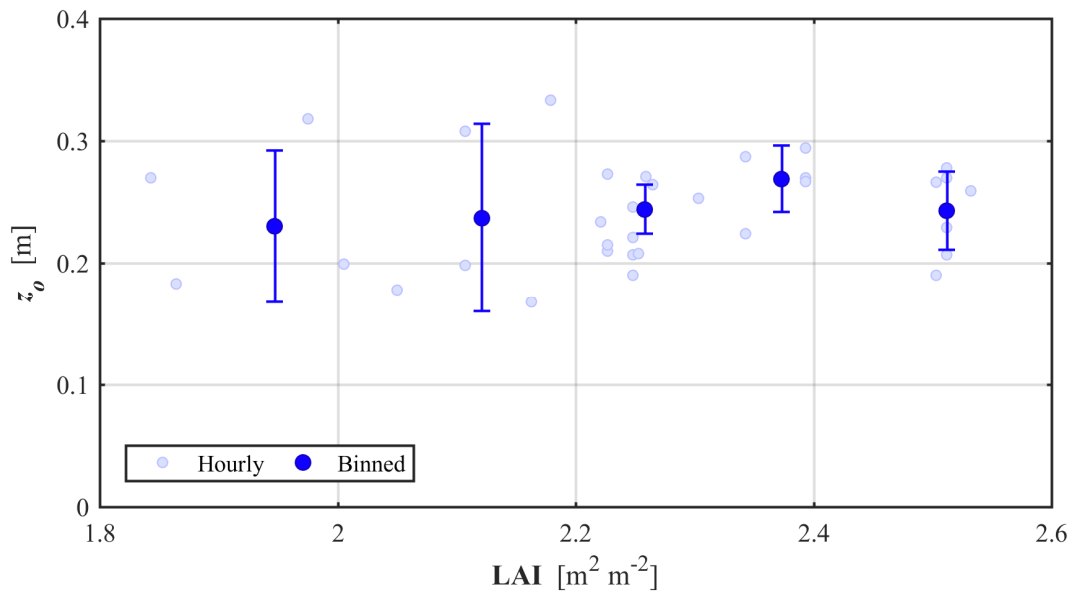


Figure 4 A plot of the roughness length (z_0) as a function of leaf area index (LAI) using the data collected at Vineyard 1 during 2015 showing the lack of a relationship between the two quantities. The error bars indicate ± 1 standard deviation.

394 The same procedure was used to identify the potential linkage between z_o and the wind
395 direction relative to the row orientation. The relative wind direction (ω) is defined as 0° when the
396 wind direction was parallel to the row direction, i.e. east to west, and 90° when the wind
397 direction was perpendicular to the row. In this case, clear sigmoidal relationships were identified
398 (Fig. 5) with the minimum z_o occurring when the winds were parallel to the row. These
399 relationships can be expressed mathematically as:

$$400 \quad z_o = \xi_{min} + \frac{\xi_{max} - \xi_{min}}{1 + e^{-\beta(\omega - \omega_o)}} \quad (23)$$

401 where ξ_{min} , ξ_{max} , β , ω_o are fitting coefficients representing the minimum z_o , maximum z_o , slope,
402 and offset in ω , respectively. Overall, with an average percent error of less than 1.5%, these
403 relationships reproduced the observed z_o quite well; the MAE ranges between 0.002 m and
404 0.008 m while the RMSD ranges between 0.002 m and 0.014 m (Table 3).

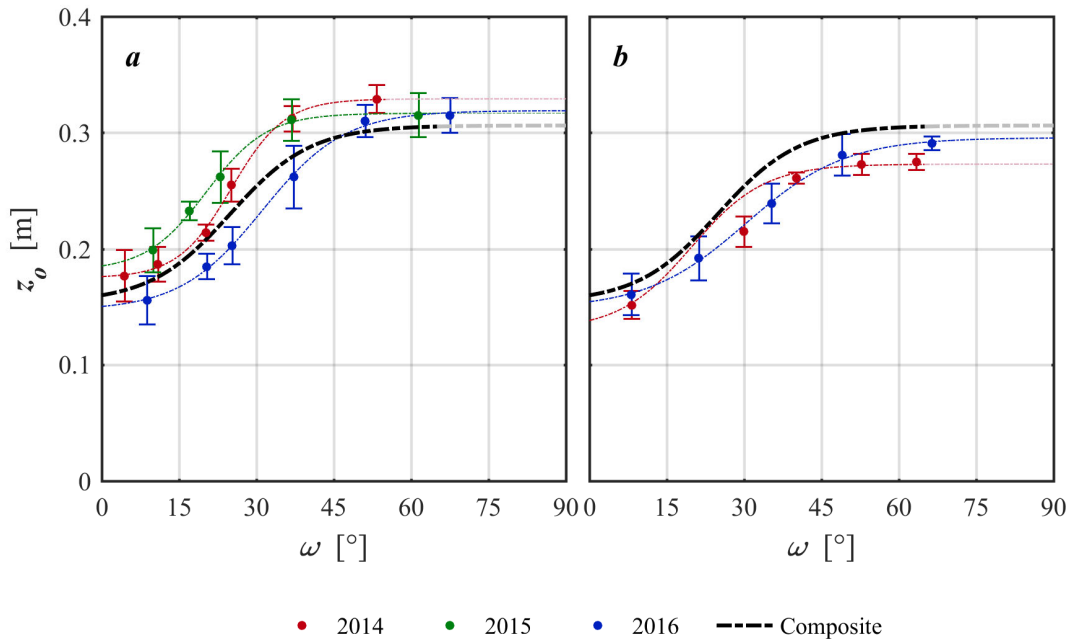


Figure 5 The best-fit sigmoidal relationships between roughness length (z_o) and relative wind direction (ω) is shown for *a*) Vineyard 1 and *b*) Vineyard 2. The error bars indicate ± 1 standard deviation. The composite curve was determined by fitting all data from Vineyard 1 and 2.

405 Nonetheless, the relationships are unique both vineyard-to-vineyard and year-to-year.
406 These variations are likely due to modest differences vine management practices that influence
407 the amount and distribution of vine biomass, thus effective roughness of the surface. For
408 example, pruning was more aggressive at Vineyard 1 in 2015 compared to other years. As a
409 result, there were fewer vine shoots intruding into the inter-row space where they can interact
410 with the wind flow. In turn, this decreases the effective roughness of the surface, particularly
411 when ω is parallel to the rows. Similarly, the lower biomass in Vineyard 2 – as discussed above,
412 the LAI of Vineyard 2 is approximately $0.25 \text{ m}^2 \text{ m}^{-2}$ lower than the LAI at Vineyard 1 – implies
413 there is less vegetation, i.e. roughness elements, for the vegetation to interact with and, therefore,
414 a lower z_o .

415 For the modeling purposes, a single composite relationship between z_o and ω was developed.
416 The resulting function has the same sigmoidal form as the curves for the individual year with
417 values of 0.1642, 0.3107, 0.1270, and 24.52 for ζ_{min} , ζ_{max} , β , and ω_o respectively (Fig. 5). While

Table 3 The error in the estimates of the roughness length when using the best-fit relationship with relative wind direction is summarized in terms of both the mean absolute difference (MAD) and root mean square difference (RMSD). The root mean square error is also partitioned between the random and systemic components.

	Vineyard 1			Vineyard 2	
Year	2014	2015	2016	2014	2016
<i>Individual Years</i>					
MAD	0.002	0.002	0.002	0.008	0.002
RMSD	0.003	0.002	0.002	0.014	0.002
RMSD_R	0.003	0.002	0.002	0.012	0.002
RMSD_S	0.000	0.001	0.000	0.008	0.001
<i>Composite</i>					
MAD	0.012	0.021	0.022	0.035	0.027
RMSD	0.015	0.023	0.025	0.036	0.028
RMSD_R	0.005	0.009	0.009	0.006	0.009
RMSD_S	0.015	0.021	0.024	0.035	0.027

418 the error, which averaged 8.3%, is greater than that seen for the individual years, it still suggests
419 reasonable agreement. Not unexpectedly, the preponderance of the error is due to systemic bias
420 when the composite relationship is used to determine z_o . For example, the composite relationship
421 systematically overestimates z_o by approximately 0.039 m at Vineyard 2 during 2016. More
422 generally, the effect of the systemic bias can be most easily seen through the decomposition of
423 the RMSD (Table 3). For the best-fit relationships determined for individual years, between 72%
424 and 100% of the error can be attributed to random error. If Vineyard 2 is neglected during 2014,
425 this range is between 95% and 100%. In contrast when the composite relationship is used, only
426 between 3% and 12% of the total error can be attributed to random error while between 88% and
427 97% of the error is systemic in nature.

428 Overview of the Model Intercomparison

429 To investigate the impact of the roughness parameterization on the modeled fluxes of
430 heat and moisture, the output from three variants of the TSEB model were compared. The first
431 version of the model (TSEB_{STD}) uses the standard parameterization estimating the roughness
432 parameters as a fraction of h_c . The second version (TSEB_{OPN}) also considers the canopy
433 geometry and vegetation density following the approach of Schaudt and Dickinson (2000). The
434 final version (TSEB_{VIN}) uses the mean d_o estimated from the observations and the relationship
435 between z_o and ω derived from the observational data. All other components of the three versions
436 of the TSEB model are the same. The models were run over both vineyards for the years 2014 to
437 2016. The comparative analysis focused on daytime non-advective periods during May through
438 August each year. Herein, daytime is defined here as period when the incident solar radiation
439 exceeded 100 W m^{-2} . Since the onset of local advection typically occurred in mid-afternoon, the
440 analysis considered the period nominally from 0700 to 1500 each day. This period includes
441 stable to unstable atmospheric conditions.

442 Model Intercomparison of the Roughness Parameters

443 As can be seen in Figure 6, the different versions of the TSEB model yielded very
444 different estimates of d_o . For all years and both vineyards, the d_o estimates from TSEB_{STD}
445 typically ranged between 1.35 m and 1.55 m and averaged 1.46 m. Overall, the typical range of
446 the d_o estimates from TSEB_{OPN}, which averaged 0.96 m, was between 0.84 m and 1.07 m. In
447 turn, the overall MAD between the d_o estimates from TSEB_{VIN} and those from TSEB_{STD} and
448 TSEB_{OPN} were 0.08 m and 0.44 m, respectively. Equivalently, the estimates from TSEB_{VIN} were
449 6% lower than TSEB_{STD}, on average; at the same time, they were 46% greater than the d_o
450 estimates from TSEB_{OPN}. If the individual vineyards are considered, the estimates of d_o from the
451 TSEB_{STD} and TSEB_{OPN} are slightly lower at Vineyard 2 compared to Vineyard 1. In both cases,
452 the difference is approximately 0.05 m and is due to the lower LAI at Vineyard 2.

453 The roughness length calculated by TSEB_{VIN} was typically less than z_o calculated by
454 either TSEB_{STD} or TSEB_{OPN} (Fig. 7). The estimates of z_o from TSEB_{STD}, which typically ranged
455 between 0.26 m and 0.30 m, varied by approximately 7% about their mean of 0.28 m. while the
456 estimates calculated by TSEB_{OPN}, which typically ranged between 0.47 m and 0.49 m and
457 averaged 0.48 m, varied by 2% about their mean. The estimates of z_o determined by TSEB_{VIN}
458 ranged between 0.17 m and 0.31 m and averaged 0.23 m. As a result, the difference in the
459 estimates of z_o from TSEB_{STD} and TSEB_{VIN} in terms of MAD was 0.06 m or, equivalently 21%.
460 More strikingly, the difference in the estimates from TSEB_{OPN} and TSEB_{VIN} was 0.25 m or
461 nearly 53%. Again, there is no evident seasonal trend in the discrepancy in the estimates. This is
462 not unexpected since the variability in the z_o calculated by TSEB_{VIN} is linked to wind direction
463 which changes on much shorter time scales. The variability in the wind direction for the hourly
464 measurements, was typically between 5° and 30°.

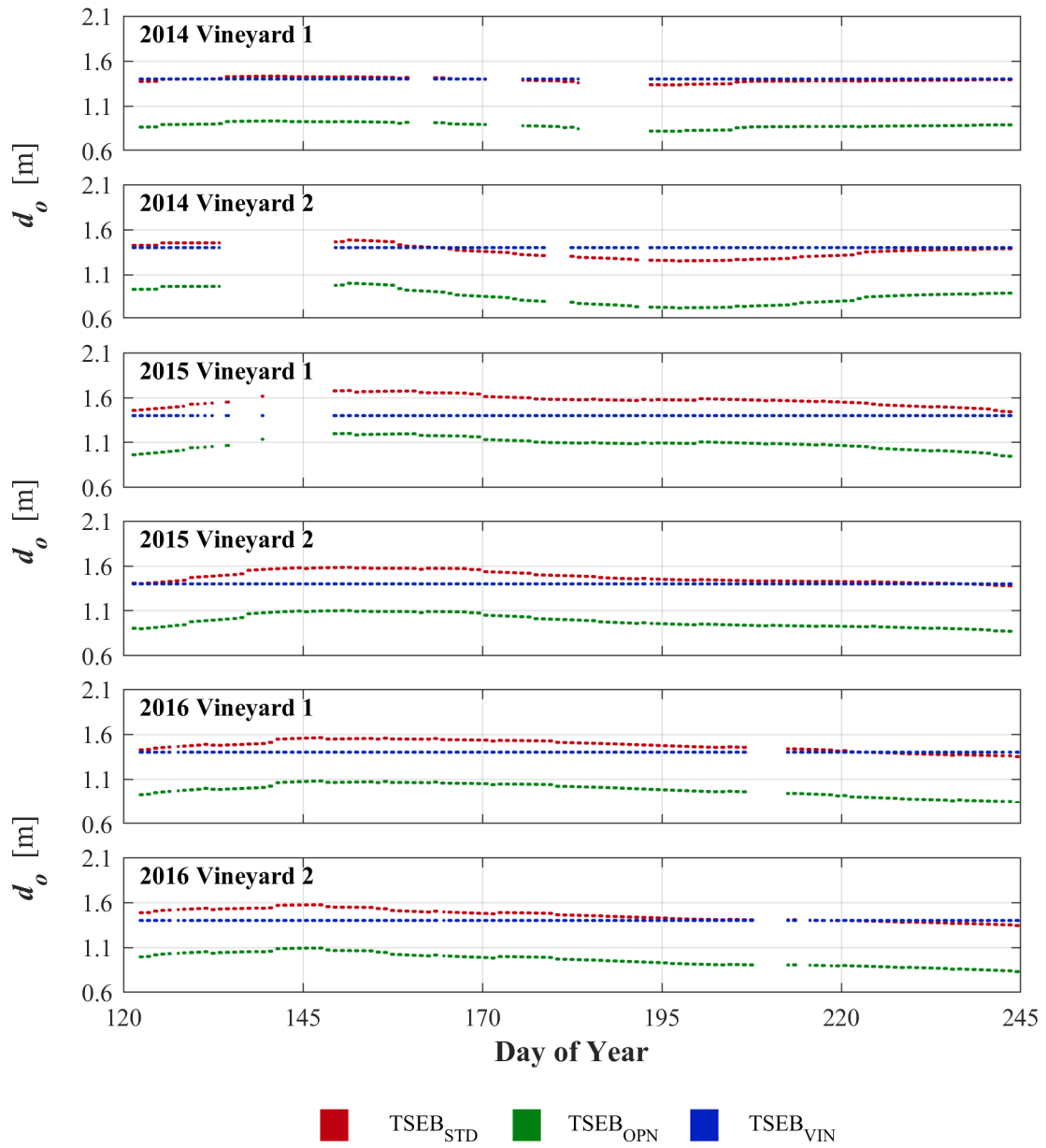


Figure 6 The estimates of displacement height from each version of the TSEB model are shown.

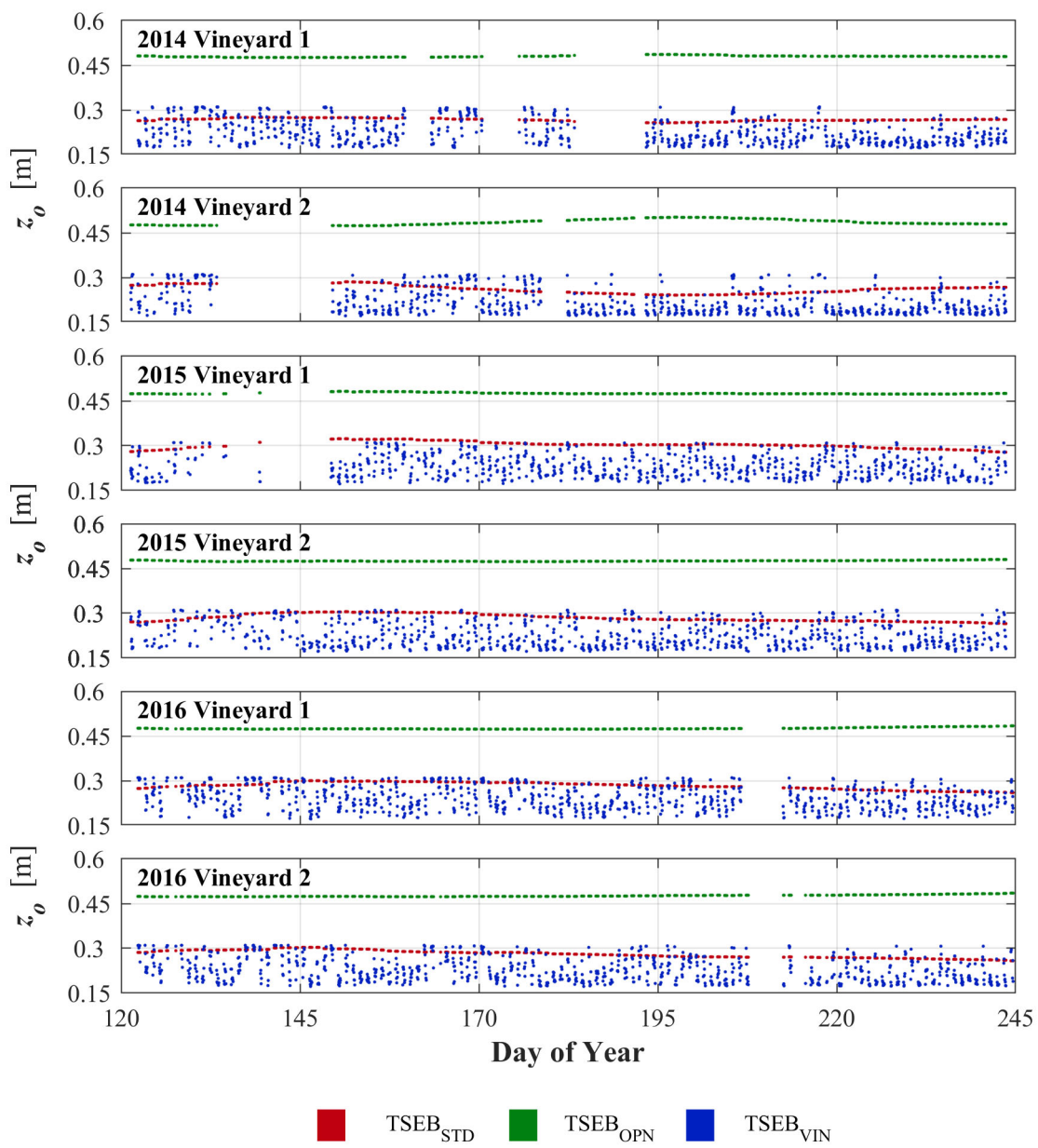


Figure 7 The estimates of roughness length from each version of the TSEB model are shown.

465 Model Intercomparison of the Turbulent Fluxes

466 The intercomparison of the model output showed consistent, albeit modest, differences in
467 the turbulent fluxes, H and λE . Moreover, since the available energy calculated by all versions of
468 the TSEB model is the same, the difference in one flux is counterbalance by a commensurate but
469 opposite difference in the other. In other words, any increase (decrease) in H (λE) is balanced by
470 a decrease (increase) in λE (H) of equal magnitude. Also, the fluxes from the canopy are
471 unchanged by changes in the roughness parameters. This is due to the linkage between r_x and T_c
472 in the TSEB model physics; because the quantity r_* is used in the calculation T_c , any change in r_x
473 results in compensatory change in T_c such that, all else being equal, the models yields the same
474 turbulent fluxes. Therefore, the changes in the turbulent fluxes due to changes in the roughness
475 parameters are the result in changes in the fluxes from the soil only.

476 Given that any change in H results in an equivalent change in λE and canopy flux is
477 unchanged by changes in the roughness parameters, the focus of this analysis is on the soil and
478 total H . Superficially, with seasonal values of MAD and RMSD ranging from slightly more than
479 1.4 W m^{-2} to 3.1 W m^{-2} and 1.7 W m^{-2} to 4.0 W m^{-2} , respectively, the difference in H calculated
480 by TSEB_{STD} and TSEB_{VIN} appears trivial. This is equivalent to an average decrease in H_s and H_{tot}
481 calculated by TSEB_{VIN} of 1.5% and nearly 3%, respectively. For the sake of comparison, the
482 increases in both λE_s and λE_{tot} were less than 1%. Additionally, by partitioning the RMSD, it was
483 found that approximately 87% of the difference can be attributed to systemic differences in the
484 modelled fluxes.

485 On an hourly timescale, however, the difference between TSEB_{STD} and TSEB_{VIN} can be
486 as much as 12 W m^{-2} or 7% and 13% and 7% for H_s and H_{tot} , respectively. As can be seen in
487 Figure 8, the largest differences occur near mid-day when the available energy is greatest. It can

488 also be seen that the differences were more mixed; although the fraction varies somewhat with
 489 time of day, on average, the flux from TSEB_{VIN} exceeded TSEB_{STD} for approximately 18% of
 490 the observational periods. This is particularly evident for Vineyard 2 where the magnitude of
 491 differences tended to be larger and more varied. For a given time of day, the range of differences
 492 in the fluxes from TSEB_{STD} and TSEB_{VIN} was typically near 14 W m⁻² at Vineyard 2 but only
 493 9 W m⁻² at Vineyard 1. Finally, it can be seen that the peak difference occurred about an hour
 494 later in the day at Vineyard 2 compared to Vineyard 1. While the cause of the differences
 495 between the two vineyards is unclear, it is hypothesized that they are due to differences in vegetation
 496 density and canopy geometry. They may also reflect the effect of using a composite function to
 497 estimate z_o which compared to the individual observed relationships tended to underestimate z_o
 498 for Vineyard 1 while overestimating it for Vineyard 2.

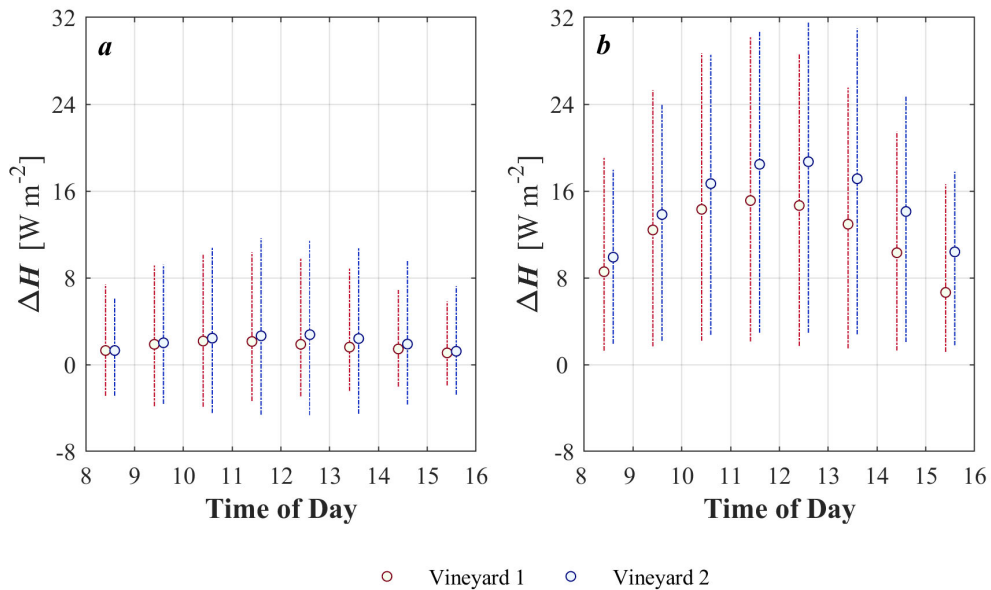


Figure 8 The mean difference of the modeled sensible heat flux calculated by *a*) TSEB_{STD} and TSEB_{VIN} and *b*) TSEB_{OPN} and TSEB_{VIN} is shown for each vineyard as a function of the time of day. The bars indicate the range of differences observed during each hourly period. Note, the data from each vineyard is staggered slightly in time to improve clarity.

499 Similarly, H_s and H_{tot} calculated by TSEB_{VIN} was modestly lower than the flux calculated
500 by TSEB_{OPN}. On average, the seasonal MAD was 13 W m^{-2} and RMSD was 14 W m^{-2} . This is
501 equivalent to decrease in H_s and H_{tot} of approximately 17% and 10%, respectively. However,
502 when considered on an hourly basis, the difference in the modeled fluxes could be as large as
503 32.0 W m^{-2} or, equivalently, 18% of H_{tot} and 10% of λE_{tot} . While the estimates of H_s , thus H_{tot} ,
504 from TSEB_{OPN} is always greater than TSEB_{VIN} during the daytime period, the same vineyard-to-
505 vineyard differences are apparent for the fluxes output by TSEB_{VIN} and TSEB_{OPN}. In this case,
506 the range of differences in the modeled fluxes averaged 21 W m^{-2} at Vineyard 1 and 24 W m^{-2} at
507 Vineyard 2. Additionally, the hourly MAD and RMSD at Vineyard 2 averaged 15 W m^{-2} and
508 17.0 W m^{-2} , respectively, compared to 12 W m^{-2} and 13 W m^{-2} , respectively, at Vineyard 1.
509 Again, this indicates that the difference in the flux estimates are more varied at Vineyard 2.
510 Finally, it can be seen in Figure 8 that the again peak difference occurred about an hour later in
511 the day at Vineyard 2 compared to Vineyard 1.

512 Given the change in the roughness parameters, especially between TSEB_{OPN} and
513 TSEB_{VIN}, the relatively small change in the turbulent fluxes might appear counterintuitive. While
514 d_o calculated by TSEB_{OPN} was, on average, 46% less than d_o calculated by TSEB_{VIN} and z_o
515 calculated by TSEB_{OPN} was, on average, 53% greater than that calculated by TSEB_{VIN}, H_{tot}
516 changed by only 10%. The limited sensitivity of the TSEB model to the roughness parameters
517 can be understood by recognizing that these quantities are primarily used to calculate the canopy
518 level and sub-canopy wind speed terms used the TSEB model to determine r_s and ultimately H_s
519 and H_{tot} (See Eq. 6 through 8 above). In the case of TSEB_{OPN} and TSEB_{VIN}, the roughness
520 parameters move in opposite directions; in other words, d_o is greater while z_o is lower for
521 TSEB_{VIN} compared to TSEB_{OPN}. As a result, the changes in the roughness parameters partially

522 compensate for one another when calculating the logarithmic quantities in the relationship for U_c
523 (Eq. 8). The sensitivity of the calculation of U_c to changes in the roughness parameters is further
524 reduced because the logarithmic quantities change more slowly than their arguments. Moreover,
525 while the wind speed just above the soil surface (U_s) changes proportionally with U_c , the rate of
526 change is lower because the exponential term in Eq. 7 must be between 0 and 1; for this study
527 that quantity ranged between approximately 0.70 and 0.75.

528 **CONCLUSIONS AND FUTURE WORK**

529 The results of this study demonstrate that z_o varies as a function of ω in open and highly
530 structured canopies such as vineyard. Specifically, a clear sigmoidal relationship was found
531 linking z_o to ω for the two vineyards considered in this study. It also showed that the relationship
532 was unique for a given vineyard and year. This suggests that other factors, such as the vegetation
533 density and vine management practices, also influence z_o . However, further study is needed to
534 identify the specific factors and quantify their role in controlling z_o . It is also needed to further
535 refine the relationships found in this study.

536 The work also showed that incorporating the methods for estimating the roughness
537 parameter developed in this study into the TSEB model results significant changes in the
538 modeled d_o and z_o . The displacement height used by TSEB_{VIN} was 1.40 m or 0.06 m less than the
539 average d_o from TSEB_{STD} and 0.44 m greater than the average d_o from TSEB_{OPN}. The effect on
540 z_o was more pronounced. Averaging 0.23 m, TSEB_{VIN} typically produced the lowest estimates of
541 z_o , while TSEB_{OPN} produced the highest estimates; these averaged 0.48 m. The average z_o from
542 TSEB_{STD} was 0.28 m. Although the differences in the roughness parameters could be large, the
543 did not impact the fluxes from the canopy and had only a modest effect on the fluxes from the
544 soil. Although the difference in flux estimates from TSEB_{STD} and TSEB_{VIN} could be nearly 12 W

545 m^{-2} at midday, MAD averaged approximately 2 W m^{-2} with TSEB_{VIN} partitioning slightly less
546 energy in H_s , thus H_{tot} , compared to TSEB_{STD}. Similarly, the difference in the flux from
547 TSEB_{OPN} and TSEB_{VIN} approached 32 W m^{-2} at midday but, on average, MAD was 13 W m^{-2} .
548 Again, H_s and H_{tot} calculated by TSEB_{VIN} was lower than that calculated by TSEB_{OPN}.

549 The results suggest that the TSEB model is largely insensitive to changes in the
550 roughness parameters. Because of this, along with the need for additional inputs that may not be
551 readily available and the site-specific nature of the relationship used to calculate z_o , the utility of
552 this approach may be limited for applications using the TSEB model. Given there is no clear
553 advantage to using the modified versions of the TSEB model, it is recommended that TSEB_{STD} is
554 used to model the fluxes over vineyards. Nonetheless, the approach may prove beneficial when
555 used with the TSEB model over other structured canopies such as orchards. It may also prove
556 valuable for improving other land surface models that are more sensitive to the roughness
557 parameters (e.g., Timmermans et al., 2007; Zhan et al., 1996); these potential uses of
558 relationships between environmental conditions and roughness deserve further evaluation.

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569 **CONFLICT OF INTEREST**

570 On behalf of all authors, there is no conflict of interest.

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