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1 **Dynamic Management Zones for Irrigation Scheduling**

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15

16 **Highlights**

- 17 • We used Sentinel 2 NDVI time-series to delineate dynamic management zones (MZ).
- 18 • Changes in MZ patterns were consistent with soil moisture spatiotemporal variability.
- 19 • Data variance fragmentation was used for daily evaluation of the dynamic MZ designs.
- 20 • Soil moisture data and model forecasts can be used to schedule MZ irrigation.

21

22 **Abstract**

23 Irrigation scheduling decision-support tools can improve water use efficiency by matching
24 irrigation recommendations to prevailing soil and crop conditions within a season. Yet, little
25 research is available on how to support real-time precision irrigation that varies within-season in
26 both time and space. We investigate the integration of remotely sensed NDVI time-series, soil
27 moisture sensor measurements, and root zone simulation forecasts for in-season delineation of
28 dynamic management zones (MZ) and for a variable rate irrigation scheduling in order to improve
29 irrigation scheduling and crop performance. Delineation of MZ was conducted in a 5.8-ha maize
30 field during 2018 using Sentinel-2 NDVI time-series and an unsupervised classification. The
31 number and spatial extent of MZs changed through the growing season. A network of soil moisture
32 sensors was used to interpret spatiotemporal changes of the NDVI. Soil water content was a
33 significant contributor to changes in crop vigor across MZs through the growing season. Real-time
34 cluster validity function analysis provided in-season evaluation of the MZ design. For example,
35 the total within-MZ daily soil moisture relative variance decreased from 85% (early vegetative
36 stages) to below 25% (late reproductive stages). Finally, using the Hydrus-1D model, a workflow
37 for in-season optimization of irrigation scheduling and water delivery management was tested.
38 Data simulations indicated that crop transpiration could be optimized while reducing water
39 applications between 11 and 28.5% across the dynamic MZs. The proposed integration of
40 spatiotemporal crop and soil moisture data can be used to support management decisions to
41 effectively control outputs of *crop × environment × management* interactions.

42

43 **Keywords:** Remote sensing; Spatial variability; Temporal variability; Precision agriculture; Soil
44 moisture; Hydrus-1D

45 1. INTRODUCTION

46 Irrigated agriculture is essential to global food production, especially because of projected
47 population growth (Döll, 2002). Irrigation water is commonly applied uniformly over an entire
48 field. Yet, field soil water content is typically non-uniform because of spatial variability in soil
49 hydraulic properties (Hawley, 1983), topography (Burt and Butcher, 1985), and vegetation growth
50 (Le Roux et al., 1995). When field spatial variability is significant (Baveye and Laba, 2014; Thorp,
51 2019), differential irrigation water management that accounts for variability may improve the cost-
52 effectiveness of irrigation (Liang et al., 2016; Martini et al., 2017) by increasing for instance water
53 use efficiency and productivity as well as decreasing nutrient leaching.

54 Precision agriculture seeks to optimize farming operations via site-specific management plans
55 that vary the application of nutrients and water across a field based on variations in soil and crop
56 conditions (Zhang et al., 2002). Field management is prescribed over contiguous areas that have
57 homogeneous soil properties and crop conditions. These areas are called management zones (MZ).
58 Different clustering methods, including *k*-mean, ISODATA, and Gaussian Mixture, are available
59 for delineating MZs based on different data sources (Galambošová et al., 2014; Martinez-
60 Casasnovas et al., 2012; Schepers et al., 2004). Commonly, yield maps, topography, remote
61 sensing data, and soil apparent electrical conductivity are used to delineate MZs (Bellvert et al.
62 2012, Liu et al., 2018; Scudiero et al., 2018; Ohana-levi et al., 2019). Recently, open access or low
63 cost remote sensing data are being used in agriculture to obtain spatiotemporal information on
64 biophysical parameters of vegetation (Fontanet et al., 2018).

65 Several researchers have defined MZs in specific fields with the goal of increasing yield and
66 decreasing water use. Inman et al. (2008) and Schenatto et al. (2015) used NDVI and other spectral
67 vegetation indices to delineate MZs with NDVI data and different crop indices. Liu et al. (2018)

68 delineated MZs based on yield and maps of different vegetation indices. Scudiero et al. (2013)
69 argued that spatial information of soil properties known to affect plant growth should guide MZ
70 delineation. They modeled maize yield spatial variability as a function of salinity, texture, carbon
71 content and bulk density, using geospatial apparent soil electrical conductivity and bare soil
72 reflectance measurements as proxies for these soil properties. A similar study was presented by
73 Reyes et al. (2019), in which MZs were defined using information of both NDVI and soil
74 properties. Georgi et al. (2018) developed an algorithm to delineate MZs automatically based on
75 remote sensing data. However, one of the disadvantages of this algorithm is that it does not work
76 properly in fields with strong time-dependent spatial patterns. All the above-mentioned studies
77 consider MZs to be static and assume no dynamic pattern during the growing season. However, in
78 fields where crop spatial patterns change over time, some researchers have advocated for MZ
79 delineation to also be dynamic (Cohen et al., 2016; Evans et al., 2013; Haghverdi et al., 2015;
80 Scudiero et al., 2018).

81 Soil moisture sensors constitute a vital tool for real-time monitoring of soil water content
82 dynamics in the field. Although sensors monitor soil water content at a single point, spatial and
83 temporal variations of soil water content and their interactions with crops can be analyzed if several
84 sensors are installed across the field (Biswas, 2014; Biswas and Si, 2011; Huang et al., 2019; Yang
85 et al., 2016). These measurements can provide information about the source of variability between
86 different MZs and aid in their delineation.

87 In this study, we integrate crop spatial and temporal information from high-resolution remote
88 sensing, soil water sensor data, and numerical model simulations to investigate irrigation
89 scheduling for dynamic management zones. Specifically, we: i.) characterize the spatial and
90 temporal dynamics of crop-soil-water relations of a maize field, ii.) delineate and evaluate

91 temporally dynamic management zones for variable rate irrigation, and iii.) provide a workflow
92 for in-season optimization of irrigation scheduling and water delivery management.

93

94 **2. MATERIALS AND METHODS**

95 **2.1 Study Site**

96 The study was carried out in a 5.8-ha maize (*Zea mays* L.) field located in Raïmat (Lleida,
97 Spain) (Fig.1). The study region has a typical semi-arid Mediterranean climate, with an average
98 summer temperature and rainfall of 24°C and 45 mm. The local climate was Mediterranean, with
99 an average annual rainfall and reference evapotranspiration (ET_0) of 341 mm and 1.060 mm,
100 respectively.

101 Land use at the study site has changed over the years (Fig. A.1 of Appendix A). Originally, the
102 site was a forest where no tillage occurred. Approximately 30 years ago, the land was converted
103 to a vineyard. The topography of the field was modified, with soil being added or removed in
104 various sections, such that the site can now be regarded as having an anthropogenic soil. In 2016,
105 two years year before this study, grapevines were removed and maize was grown at the site.

106

107 **2.2 Sowing and Irrigation**

108 All agronomic management and design at the field site was implemented by cooperators
109 without our input. The field was sectioned into four plots that were each sowed with a different
110 maize variety (Fig.1). The varieties were, from west to east: p0937 (DuPont Pioneer, Johnston,
111 IA), d6980 (DEKALB Genetics Corporation, Dekalb, IL), p1524 (DuPont Pioneer), and d6780
112 (DEKALB). All plots were sown on May 3, 2018, at a sowing density of 90000 seeds·ha⁻¹. Plants
113 started to emerge on May 12, 2018. Data from the seed companies indicated that the varieties

114 sowed on the west and east edges (p0937 and d6780) had a faster vegetative growth than d6980
115 and p1524. However, all varieties were anticipated to reach full maturity between 125 to 165 days
116 after sowing. All the varieties were harvested on September 22, 2018.

117 The field was irrigated with a solid set sprinkler system (Nelson Irrigation Corporation, Walla
118 Walla, WA), with sprinklers located at a 15 x 15 m spacing. Water was delivered at a rate of 6.5
119 L·m⁻²·h⁻¹. Irrigation was uniformly applied over the field with scheduling and depths determined
120 using a crop coefficient approach (FAO56). For most of the site, irrigation ended 115 days after
121 sowing. But, in two 0.3-ha sections at the north-east end of the site, irrigation was halted 74 days
122 after sowing due to soil waterlogging.

123 **2.3 Soil, Environment, and Crop Measurements**

124 Field data were collected between May and September 2018. Soil moisture, soil and crop
125 parameters, environmental variables, and NDVI time-series were measured. In May 2018, 33
126 capacitive EC-5 soil moisture sensors (METER Group, Pullman, WA, USA) were installed at 11
127 locations named P1, P2, ..., and P11 (Fig.1). The sensors were installed at 15, 35, and 50 cm
128 depths. Water content data were registered every 30 minutes using an EM5b data logger (METER
129 Group). The manufacturer's generic sensor calibration was used, which has a reported accuracy ±
130 0.03 cm³·cm⁻³ (Campbell and Devices, 1986)

131 At each soil moisture station, three disturbed soil samples were collected at 0-5, 5-35, and 30-
132 60 cm depth for organic matter (OM) and soil texture analyses. The Walkley-Black method was
133 used to measure OM (Nelson and Sommers, 1996), whereas soil particle size distribution was
134 measured according to the hydrometer method (Gee and Bauder, 1986). Particles were categorized
135 into the following size classes: clay (soil particle diameter, $D < 0.002$ mm), fine silt ($0.002 < D <$
136 0.02 mm), coarse silt ($0.02 < D < 0.05$ mm) and sand ($0.05 < D < 2$ mm). Undisturbed soil cores

137 were also collected at the same locations and depths for measuring soil hydraulic properties.
138 Saturated hydraulic conductivity was measured with a KSat device (METER Group). Soil water
139 retention measurements were obtained using Hyprop and WP4C instruments (METER Group).
140 The Hyprop device utilizes an evaporation method (Schelle et al., 2013) and was used to obtain
141 retention data from 0 to -85 kPa, whereas the WP4C device implements a chilled mirror dew point
142 technique and was used to obtain measurements down to -300 MPa. The van Genuchten equations
143 (van Genuchten, 1980) were used to model the retention data and the soil unsaturated hydraulic
144 conductivity. In the van Genuchten model, the Ksat parameter was set to the saturated conductivity
145 measured with the KSat device, the saturated water content parameter (θ_s) was set to the soil
146 porosity estimated by the Hyprop device, and the residual water content parameter (θ_r) was set to
147 the minimum water content recorded by the WP4C device. The van Genuchten shape parameters
148 α and n were determined by fitting the model retention function to the measured data using the
149 RETC software package (van Genuchten et al., 1991). Principal component analysis (PCA) (Abdi
150 and Williams, 2013; Martini et al., 2017) was used to investigate the relationships between soil
151 texture, OM, bulk density, and hydraulic parameters. The PCA calculations were done with
152 Statistica 12 (StatSoft Inc. Tulsa, OK, USA).

153 A weather station consisting of an ECRN-100 rain gauge (METER Group), a cup anemometer
154 (Davis Instruments, Hayward, CA, USA), and PYR pyranometer and VP-4 relative humidity and
155 temperature sensors (METER Group) was installed 150 m from the north-east corner of the field.
156 The measured temperature, wind speed, relative humidity, and solar radiation were used to
157 calculate daily reference evapotranspiration (ET_0) using the Penman Monteith equation as
158 specified in FAO Irrigation and Drainage Paper No. 56 (Allen et al, 1998; hereafter “FAO56”).
159 The estimated ET_0 was converted into daily water requirements or potential evapotranspiration

160 (ET_c) using the maize crop coefficient (k_c) from FAO56. Maximum and minimum daily
161 temperature measurements were used to calculate growing degree days (GDD) according to
162 FAO56 and to determinate reference maize growing stages (Ritchie et al., 1997).

163 Remote sensing data obtained from Sentinel 2 were used to determine normalized difference
164 vegetation index ($NDVI$) (Rouse et al., 1974),

$$NDVI = \frac{(NIR - Red)}{(NIR + Red)} \quad (1)$$

165 where NIR and Red are measured reflectance values in the near-infrared and visible red regions,
166 respectively. $NDVI$ was used to evaluate spatial variability in the field. Remote sensing data were
167 downloaded with 10-m spatial resolution every 5 days unless there was cloud coverage. The first
168 and last images downloaded were the 15th and 135th day after sowing. Remote sensing data were
169 downloaded from Google Earth Engine web page (<https://earthengine.google.com>).

170

171 **2.4 Management Zones Delineation**

172 $NDVI$ was used to characterize the spatial variability of crop vigor through the growing season.
173 A k-means (also known as “fuzzy c-means”) unsupervised clustering algorithm (Odeh et al., 2010)
174 was used to classify the $NDVI$ data into temporally dynamic MZs. The Grouping Analysis tool in
175 ArcMap 10.4.1 (ESRI, Redlands, CA) was used for the MZ delineation. Anytime a new Sentinel
176 2 $NDVI$ scene was available at the site, a new MZ scheme was delineated. Designs having 2 to 6
177 MZs were considered. The Calinski–Harabasz criterion (CHC) (Harabasz et al., 1974), Eq. (2),
178 was used to evaluate the clusters and MZ delineations and select the optimum number of MZs.
179 The CHC , also known as a pseudo F-statistic, measures the ratio of between-MZ differences and
180 within-MZ similarity. It is formulated as:

$$CHC = \frac{BMZSS/(MZn - 1)}{WMZSS/(N - MZn)} \quad (2)$$

181 where N is the number of pixels, MZn is the number of considered zones, $BMZSS$ is the between-
 182 zones sum of squares, and $WMZSS$ is the within-zone sum of squares. Large CHC values indicate
 183 high within-MZ homogeneity and between-MZ heterogeneity.

184 The $NDVI$ averages and maximum and minimum values within each MZ were calculated for
 185 further comparison between different MZs. MZs were not defined for the beginning of the season
 186 (0-20 day after sowing) because plants had not yet germinated or were not big enough to influence
 187 $NDVI$, and for the end of the season (beyond 130 days after sowing) because in that period the
 188 crop is in a late phenological stage and not irrigated. Differences in soil properties across MZs
 189 over time were assessed using a Kruskal-Wallis (Kruskal and Wallis, 1952) rank test (i.e., a non-
 190 parametric analysis of variance), calculated with Statistica 12.

191 Additionally, we considered an alternative static delineation scheme, subdividing the site into
 192 four contiguous fields corresponding to the planted maize varieties. The CHC was calculated for
 193 each available $NDVI$ scene to compare the variety-based MZ approach to the dynamic $NDVI$ -
 194 based MZ delineation.

195

196 2.5 Management Zone Available Water

197 Soil-water status for the MZs was modeled as plant available water (AW) (Liang et al., 2016;
 198 Vellidis et al., 2016; Zurweller et al., 2019):

$$AW^j(t) = \frac{1}{Z_T} \sum_m \left(\frac{\theta^{j,m}(t) - \theta_{wp}^{j,m}}{\theta_{fc}^{j,m} - \theta_{wp}^{j,m}} \right) \Delta Z^m \quad (3)$$

199 where $AW^j(t)$ is the profile average available water at monitoring station j and time t , m
200 indexes the measurement depths, Δz^m (cm) is the depth increment associated with the moisture
201 sensor at depth m , $Z_T = \sum \Delta z_m$ (cm) is the total soil profile depth, $\theta^{j,m}$ ($\text{cm}^3 \cdot \text{cm}^{-3}$) is soil water
202 content, $\theta_{\text{wp}}^{j,m}$ ($\text{cm}^3 \cdot \text{cm}^{-3}$) is the wilting point (water content at -1500 kPa), and $\theta_{\text{fc}}^{j,m}$ ($\text{cm}^3 \cdot \text{cm}^{-3}$) is
203 field capacity (determined using the simulated soil drainage method of Twarakavi et al. (2009)).
204 The AW for a MZ was defined to be the average AW for all monitoring stations located within the
205 MZ. Note that the MZ design changed over the growing season, so the MZ membership of some
206 stations also changed. In addition to the CHC calculation on the $NDVI$ data, the spatiotemporal
207 variability of AW was also used for in-season evaluation of the dynamic MZ-design. Following
208 Fraisse et al., (2001), we calculated the daily weighted within-MZ AW variance (4),

$$S_{MZ_i}^2 = \frac{N_{S_i} N_t}{N_S N_t} \times \frac{1}{N_{S_i} N_t} \sum_{j,k} [AW^j(t_k) - \overline{AW}_i]^2 \quad (4)$$

209 where $S_{MZ_i}^2$ is the daily weighted AW variance within management zone i ; j indicates the
210 monitoring stations within management zone i ; k indicates the measurement times during the
211 current day; N_{S_i} is the number of stations in management zone i ; $N_S (= 11)$ is the total number of
212 stations in the field; $N_t (= 48)$ is the number of measurements per day (every 30 min), AW^j is
213 defined by (3), and \overline{AW}_i is the average profile AW across monitoring stations in management zone
214 i and measurement times in the current day. The total within-zone variance is equal to the sum of
215 the weighted within-zone variances, $S^2 = \sum_i S_{MZ_i}^2$. By comparing S^2 with the total daily field-wide
216 AW variance, it is possible to determine how much was gained in terms of AW uniformity by
217 dividing the field into MZs (Fraisse et al., 2001).

218

219 3. RESULTS AND DISCUSSION

220 3.1 Soil Properties

221 Soil texture, organic matter (OM) content and bulk density (ρ_b) values measured at each station
222 are reported in Table 1. The soil texture classes (USDA system) of samples taken from the 11
223 locations were clay loam (42.4 % of samples), loam (42.4%), and silty clay loam (15.2%).
224 Locations on the east side (P1, P6, P7, P11) of the field had, on average, lower sand and higher silt
225 and clay contents than those on the west side. Average OM contents ranged between 0.57 and 1.96
226 %, which is typical for agricultural soils in this region (Romanyà and Rovira, 2011). Fitted and
227 measured parameters for the soil hydraulic properties at each station are reported in Table 2.
228 Consistent with the spatial trend in soil texture noted previously, the SWRCs measured on the east
229 side of the study site (stations P1, P6, P7, P11) had lower fitted n values than in the rest of the site.
230 On the wet end of a retention curve, a lower n value corresponds to a more gradual transition in
231 water content as pressure head changes. Figure A.2 of Appendix A compares SWRCs observed at
232 the locations on the west (P9) and east (P11) sides of the field.

233 The principal component analysis (PCA) indicated that eight principal components were
234 needed to explain 95% of the variability in the soil dataset. The first three components, PC1
235 (30.9%), PC2 (18.6%), and PC3 (15.9%), explained around two thirds of the variance in the soil
236 dataset. Particularly, PC1 indicated that clay content clustered (was positively correlated) with θ_{wp} ,
237 θ_{fc} , and α . The PC1 also indicated that clay content was negatively correlated with sand content,
238 θ_r , and n . Further detail about PC1, PC2, and PC3 are reported in Fig. A.3 of Appendix A.

239

240 3.2 Remote Sensing and Dynamic Management Zones Delineation

241 The site average, minimum, and maximum $NDVI$ values for each available Sentinel 2 scene
242 are reported in Fig. 2a. Changes in averaged $NDVI$ generally corresponded to the evolution of ET_c

243 at the site, consistent with reports for maize grown in Mediterranean climates in other studies
244 (Segovia-Cardozo et al., 2019; Toureiro et al., 2017). Figure 2b shows that cumulative input water
245 (irrigation and precipitation) (618 mm) exceeded by 10.2% the site-wide cumulative ET_c (561
246 mm). At the bottom of Fig. 2, reference growing stages for maize at the site are shown (Ritchie et
247 al., 1997). Varieties needed between 120 and 130 days to reach maturity. Thus, we considered the
248 reference growing stages to be representative for all maize varieties grown at the site. $NDVI$ and
249 ET_c were low during the early vegetative stages, had maximum values during the late vegetative
250 stage (VT) through the beginning of the reproductive stages (R1-R6), then decreased after R6. The
251 temporal changes of $NDVI$ at the site are comparable to those observed in other studies on maize
252 (Viña et al., 2004). In the early vegetative stages (V0 to V5), the $NDVI$ range of each Sentinel 2
253 scene was narrow. In later vegetative stages and early reproductive stages, the $NDVI$ ranges were
254 much larger, indicating considerable variability in crop status (greenness, health) at the site.

255 Figure 3a shows the spatiotemporal changes of $NDVI$ at the sites. Areas with high and low
256 $NDVI$ were observed at the site throughout the growing season. However, the $NDVI$ spatial
257 patterns changed over time, suggesting that homogeneous or static site-specific irrigation
258 management may be inadequate to address crop needs over time at this site. Figure 3b shows the
259 dynamic MZ delineation obtained with unsupervised clustering of the $NDVI$ data. The number of
260 MZ and its spatial distribution changed throughout the growing season. At the beginning of the
261 season, until 50 days after sowing, it seems that the optimal number of homogeneous MZ was
262 three. The MZ1 covered the north-west side of the site and had the highest $NDVI$ values; the MZ2
263 had intermediate $NDVI$ and spanned across the south of the site until the 45th day after sowing and
264 after that over the south-west only. The MZ3 had lower $NDVI$ values and was initially the north-
265 eastern side of the site, then covered the entire western side of the field at 45 days after sowing.

266 From the 50th day after sowing, the *CHC* indicated that four clusters were best at identifying areas
267 with homogeneous *NDVI*. MZ1 and MZ2 remained relatively similar to their early season
268 delineations. The MZ4 identified an area of moderately low *NDVI* at the south-eastern portion of
269 the site, whereas MZ3, on the north-eastern side of the site, was characterized by the lowest *NDVI*
270 values. The spatial patterns of the four MZs changed only slightly over time, until the 130th day
271 after sowing, when the size of MZ3 increased remarkably while MZ4 decreased. The
272 unsupervised *NDVI* clustering was compared to dividing the site into four blocks, one for each
273 maize variety. Figure 3c shows the *CHC* values for *NDVI* clustering into dynamic MZ and into
274 varietal-based blocks through the growing season. The dynamic MZ-design strategy had larger
275 *CHC* values for the entire growing season than the variety-block strategy, indicating that the
276 dynamic MZs identified by unsupervised clustering had more homogeneous *NDVI* than the
277 varietal blocks.

278 Figure 3a shows contrasting *NDVI* values between the eastern and western side of the field,
279 especially visible along the boundary between the d6980 and p1524 varieties. The boundary
280 between the d6980 and p1524 varieties seemed to be a big factor in the determination of the
281 boundary between eastern (MZ1 and MZ2) and western (MZ3 and MZ4) zones from 55 to 120
282 days after sowing (Fig. 3b). Figure A.1.f of Appendix A shows the p1524 and d6780 varieties
283 doing relatively poorly in July 2018. Therefore, in addition to different soil hydraulic properties
284 on the east side of the field, crop genetics (e.g., pest resistance, germination rate between the
285 varieties) and uneven management (e.g., mechanical sowing, fertilization, soil tillage) could have
286 been contributing factors to the poor performance of the p1524 and d6780 varieties. Changes in
287 MZ delineation over time led to some changes in MZ membership for certain soil-water
288 monitoring stations (Table 3). These changes occurred frequently in the early vegetative stages

289 (until 54 days after sowing). No MZ membership change occurred in the late vegetative and
290 reproductive stages. The MZs were characterized by contrasting soil properties throughout the
291 season. The MZ had significantly ($p < 0.05$) different PC1 scores throughout the season according
292 to the Kruskal Wallis test: MZ1 and MZ2 were characterized by low PC1 scores, whereas MZ3
293 and MZ4 were characterized by the highest PC1 scores (Fig. A.3 of Appendix A).

294

295 **3.3 NDVI and Water Applied**

296 Changes in *NDVI* and *AW* across MZs are depicted in Fig. 4a (MZ1), 4b (MZ2), 4c (MZ3),
297 and 4d (MZ4). Through the growing season, *NDVI* in MZ1 and MZ2 was higher than in MZ3 and
298 MZ4. Furthermore, *NDVI* was slightly higher in MZ1 than in MZ2. Average *AW* in MZ1 was
299 close to 1 (i.e., water content was near θ_{fc}) throughout the entire growing season. Average *AW* in
300 MZ2 was greater than 1 at the beginning of the season (until 45 days after sowing) and then very
301 close to 1 through the end of the growing season. Portions of MZ3 and MZ4 had lower *NDVI*
302 values than MZ1 and MZ2. In these areas, irrigation was likely excessive. *AW* was considerably
303 higher than 1 for the entire vegetative growth of maize and during the early reproductive stages.
304 Once irrigation was halted in the northeastern corner of the site (i.e., approximately over the area
305 comprised by MZ3) at 74 days after sowing, the *AW* in MZ3 gradually decreased until the end of
306 the season, while *NDVI* in MZ3 remained stable. Halting irrigation in the northeastern corner of
307 the site had little-to-no effect on the spatial extent of MZ3 and the other MZs, as shown in Fig.
308 3c. The analysis of the daily total within-MZ *AW* variance (S^2) provided further support for the
309 use of *NDVI* to identify areas with similar *AW* conditions at the site. In Fig. 4e, the calculated total
310 MZ variance is normalized by the daily whole-site *AW* variance. Especially beyond 45 days after
311 sowing (the beginning of the VT growth stage), the normalized within-MZ variance is much less

312 than 1, showing that a large part of the total *AW* variance was explained by splitting the site into
313 dynamic MZs delineated based on an analysis of *NDVI*. Fraisse et al. (2001) used yield within-
314 zone variance to evaluate soil-derived MZs at the end of the season. Our results suggest that daily
315 $AW S^2$ could also be used for in-season evaluation of management zone designs.

316 The *AW* and *NDVI* time series data show that soil water content was a major factor
317 determining *NDVI* spatiotemporal variability at the site. *NDVI* is an indicator of the canopy
318 vegetative growth, and several studies have found positive correlations between *NDVI*, *AW*, and
319 canopy vigor in different crops (Scudiero et al., 2014; West et al., 2018). However, those studies
320 were for water scarce conditions. It is well known that crop water stress and reductions in canopy
321 growth can occur to either deficit of water (i.e. drought) or excess of water (i.e. flooding) (Feddes
322 et al., 1978). In the current study, where maize was grown under nearly waterlogged conditions
323 for most of the growing season (Fig. 4), changes in *NDVI* and *AW* between consecutive Sentinel
324 2 scenes were negatively correlated, with Pearson *r* equal to -0.64 (MZ1), -0.87 (MZ2), -0.79
325 (MZ3), and -0.83 (MZ4) (all significant at $p < 0.05$). Thus, as reported in different studies (Long et
326 al., 2015; Quebrajo et al., 2018; Scudiero et al., 2018; Shanahan et al., 2008), *NDVI* data alone
327 should not be used to make irrigation management decisions; *NDVI* (and/or other plant canopy
328 information) should be integrated with soil information to properly understand plant processes at
329 a site.

330

331 **3.4 Irrigation Scheduling Simulations**

332 With respect to within-season management decisions, one way to make a connection between
333 *NDVI*-based dynamic management zone delineation and soil conditions would be to use a
334 simulation model to make within-season forecasts of soil and crop conditions for different

335 management options. Several authors have simulated different irrigation strategies, for different
336 purposes, in order to define the most appropriate irrigation strategy (Autovino et al., 2018; Haj-
337 Amor and Bouri, 2020; Sakaguchi et al., 2019). In the remainder of this paper, we determine a
338 hypothetical optimal irrigation schedule for each growing stage using the simulation/optimization
339 approach developed by Fontanet (2019). We first show that a physically based simulation model,
340 Hydrus-1D (Šimůnek et al., 2016), is consistent with NDVI-based zoning by simulating the field
341 experiment and demonstrating agreement between measured *AW* and simulated available water
342 (*SAW*), as well as showing a correspondence between simulated transpiration (ST_a) rates and
343 *NDVI*. Next, we use the calibrated model to investigate what-if irrigation scenarios, calculating a
344 hypothetical irrigation scheduling table for each dynamic MZ that could have been generated from
345 *NDVI* within season to guide irrigation.

346

347 **3.4.1 Hydrus 1-D available water and transpiration simulations**

348 The well-known Hydrus-1D model solves the Richards Equation numerically to simulate
349 variably saturated water flow and root water uptake in soils. The model inputs and
350 parameterizations used in our simulations are detailed in Appendix B. Simulations of the
351 experiment for differing monitoring locations all used the same inputs and parameters except for
352 (i.) the soil hydraulic properties, which were measured at each station during the field campaign
353 (Table 2), and (ii.) the irrigation boundary condition, which differed only for stations P10 and P11
354 because irrigation was stopped during the experiment.

355 In Fig. 5, daily observed *AW* for each station is compared with daily-simulated available water
356 (*SAW*). Generally good agreement between *AW* and *SAW* existed for all stations, although it is
357 acknowledged that the *AW* time courses were relatively non-dynamic. Still, the simulations were

358 done using independently measured hydraulic properties and without any calibration, so the
359 agreement is quite good (modeling details can be found in Appendix B). Missing data towards the
360 end of the season in P7 was due to rodents chewing on the sensor cables.

361 Figure 6 shows the weekly-simulated actual transpiration (ST_a) at each MZ and the potential
362 transpiration (T_p) at the site. At MZ1 and MZ2, ST_a weekly averages were always equal or near
363 the potential transpiration. At MZ3 and MZ4, ST_a weekly values were remarkably lower than the
364 potential. There was good correspondence between ST_a and $NDVI$ at each MZ, with a Pearson r
365 of 0.6 (MZ1), 0.51 (MZ2), 0.69 (MZ3), and 0.82 (MZ4). In agreement with the results discussed
366 for $NDVI$ and AW data (section 3.2. *Remote Sensing and Dynamic Management Zones*
367 *Delineation*), low ST_a values at MZ3 and MZ4 were due to waterlogging (root water uptake and
368 transpiration is reduced in the model whenever simulated soil water content exceeds a threshold
369 value; see Appendix B). Stations in MZ3 and MZ4 (see Table 3) had AW and SAW over 1 for
370 most of the growing season (Fig. 4).

371

372 **3.4.2 Irrigation scheduling for within-season decision making**

373 We adopted the method of Fontanet (2019) to investigate optimal irrigation scheduling for
374 dynamic MZs. In this method, irrigation of duration τ [T] is prescribed whenever the soil moisture
375 content decreases below a critical threshold level (h_{th}) as indicated by readings from a soil water
376 pressure head sensor(s). The irrigation rate is assumed to be a fixed constant for a given irrigation
377 system. The recommended duration and threshold are determined using a simulation/optimization
378 procedure. Simulations are made using forecasted daily or weekly crop water demand (reference
379 ET_0) and a range of values for the irrigation scheduling parameters, h_{th} and τ . The optimal
380 parameter values are those that maximize seasonal transpiration in the simulations (transpiration

381 being, for many agronomically important crops, proportional to marketable yield). In adapting the
382 simulation/optimization method, we make separate recommendations for each MZ, and update
383 them whenever there is a change in MZ station membership. The recommended values of h_{th} and
384 τ for a given MZ are the average values determined for monitoring stations within the zone. For
385 simplicity, we use in this example the known daily potential ET_0 for the forecasted model boundary
386 condition (rather than historical data which would be necessary for actual within-season forecasts).
387 Haghverdi et al. (2015) and Liang et al. (2016) proposed calculating crop water requirements as a
388 function of root growth since the soil depth to refill increases as roots grow deeper. Similarly, in
389 our simulations, we triggered irrigation based on readings from progressively deeper sensors as
390 the season progressed. In principle, when multiple sensor depths are available, the sensor depth
391 could be treated as an additional optimization parameter. Full details on our implementation of the
392 Fontanet, (2019) procedure are given in Appendix C.

393 Although the Fontanet (2019) method prescribes an optimized irrigation schedule, in practice
394 a grower may not be able to irrigate exactly according to a schedule and sensor readings,
395 particularly when there are multiple management zones. Therefore, we also calculated
396 recommended irrigation durations (or, equivalently, irrigation amounts) for soils that have become
397 dryer than the “optimal” irrigation trigger point.

398 The resulting irrigation scheduling calendar for dynamic-MZ irrigation is presented in Table
399 4. Optimal irrigation strategies for each growth stage are shown in bold. The other table entries
400 show irrigation recommendations for field sections that are dryer than the optimal trigger point.
401 Across all MZs, the optimal irrigation durations were in the range of 1.9 to 2.6 h. However, the
402 triggering thresholds varied by location. Thresholds for MZ1 and MZ2 were in the range of -18.3
403 to -30 kPa, whereas the range for MZ3 and MZ4 was -10 to -20 kPa. In general, the

404 recommendations are for more frequent and slightly shorter irrigations in MZ3 and MZ4, which
405 are located on the east side of the field and feature finer textured soils. With the specific Hydrus-
406 1D model parameterization used in the current study, uptake and transpiration are penalized
407 whenever any portion of the soil approaches saturation. The recommendation
408 of somewhat shorter, more frequent irrigations on the east side is due to optimization's aversion
409 to creating overly wet soil conditions near the surface, such as may occur (albeit briefly) during a
410 longer irrigation.

411 Table 5 compares seasonal transpiration and irrigation simulated with optimal scheduling
412 versus the amounts obtained simulating the field experiment. For MZ1 and MZ2, the optimal
413 schedule recommended 11 to 13 % less water and increased transpiration by 5 to 8 %. For MZ3,
414 29 % less water was recommended, with an increase in transpiration of 24 %. And for MZ4, a 17
415 % reduction in irrigation corresponded to a massive 53% increase in transpiration. These results
416 are consistent with our earlier findings and discussion indicating the field was over-irrigated,
417 especially in MZ3 and MZ4.

418

419 **4. CONCLUSIONS**

420 Irrigation scheduling is complicated due to the spatial and temporal variability of a number of
421 variables and parameters. In this work, we investigated a workflow for improved precision
422 irrigation scheduling using data from a field where four maize varieties were sown. The workflow
423 is based on dynamic MZ delineation with unsupervised *NDVI* clustering. This study demonstrates
424 that delineation of MZs based on *NDVI* clustering was able to statistically represent within-field
425 spatial variability better than delineating MZs only based on maize varieties. Additionally, the
426 optimal number and spatial configuration of the MZs were found to change over the growing

427 season. The highest number of MZs was four. The MZ1 and MZ2 corresponded to field sections
428 where NDVI values reflected a typical maize crop performance, whereas MZ3 and MZ4 featured
429 relatively low *NDVI* values indicative of poor maize growth.

430 Soil water content showed that the variation in crop performance was attributable to soil
431 hydraulic properties, soil available water, and over-irrigation. Further, a relationship existed
432 between NDVI and soil available water. The results indicated that soil available water could
433 potentially also be used for, or incorporated into, in-season evaluation of management zone
434 designs.

435 Lastly, we proposed a method of combining dynamic management zone delineation with
436 Hydrus 1-D model forecasts for irrigation scheduling. The field experiment was first simulated to
437 confirm the model parameterization and demonstrate its consistency with the obtained NDVI and
438 soil water content data. We then used model simulations to determine an optimal zonation and
439 irrigation calendar for different crop growth stages that could have been generated and updated in
440 real time during the season. Simulations with the optimized irrigation schedule produced an
441 increase in transpiration and a decrease in water use as compared to the field trial (which, again,
442 was over-irrigated). The improvement was especially remarkable for MZ3 and MZ4, where
443 irrigation was reduced by 28.5 and 16.6 %, and transpiration increased by 23.9 and 52.6 %,
444 respectively.

445 In summary, we note that although NDVI is useful for dynamically delineating management
446 zones, for irrigation scheduling it is recommended that NDVI be combined with some additional
447 measure of soil conditions. Low NDVI values may be indicative of poor crop performance, but
448 without other information it is not possible to determine the cause nor recommend a remedial
449 irrigation or management practice.

450

451 **Appendix A. Supplementary figures**

452 Supplementary material related to this article can be found, in the online version, at doi: #

453

454 **Appendix B. Hydrus -1D Simulations**

455 Hydrus-1D (Šimůnek et al., 2016, 2008) was used to simulated soil moisture dynamics and
456 water balance components at each monitoring station. Each simulation spanned 105 days, from the
457 18th to the 123rd day after sowing. The 60 cm soil profile consisted of three layers/materials, as
458 specified in Table 2. Soil hydraulic properties were specified using the van Genuchten-Mualem
459 model (van Genuchten, 1980) as follows:

$$\theta(h) = \begin{cases} \theta_r + \frac{\theta_s - \theta_r}{(1 + |\alpha h|^n)^m} & h < 0 \\ \theta_s & h \geq 0 \end{cases} \quad (\text{B.1})$$

460 and

$$K(h) = K_s S_e^{1/2} \left[1 - (1 - S_e^{1/m})^m \right]^2, \quad (\text{B.2})$$

461 where θ ($\text{cm}^3 \cdot \text{cm}^{-3}$) is the volumetric water content; h is the soil water pressure head (cm); θ_s
462 ($\text{cm}^3 \cdot \text{cm}^{-3}$) is saturated water content; θ_r ($\text{cm}^3 \cdot \text{cm}^{-3}$) is residual water content; K_s ($\text{cm} \cdot \text{d}^{-1}$) is
463 saturated hydraulic conductivity; n and α are shape parameters; $S_e = \frac{\theta - \theta_r}{\theta_s - \theta_r}$; and $m = 1 - 1/n$.

464 In Hydrus, root water uptake is simulated using a sink term S which has three parts, the
465 potential transpiration rate (T_p) ($\text{cm} \cdot \text{d}^{-1}$), the root density distribution (β) (cm^{-1}), and the
466 dimensionless water stress function ($\alpha(h)$):

$$S(h, z, t) = \alpha(h, z, t) \beta(z, t) T_p(t) \quad (\text{B.3})$$

467 The actual transpiration rate (T_a) ($\text{cm} \cdot \text{d}^{-1}$) is calculated by integrating Eq. (B.3) over the root zone

468 L_R :

$$T_a = \int_{L_R} S(h, z, t) dz = T_p \int_{L_R} \alpha(h, z, t) \beta(z, t) dz \quad (\text{B.4})$$

469 Root depth was measured twice a month during the field campaign at P9 station. This
470 information was used to parameterize the Hydrus root growth module.

471 Water stress ($\alpha(h)$) was modeled using the Feddes et al. (1978) function:

$$\alpha(h) = \begin{cases} \frac{h - h_4}{h_3 - h_4} & h_3 > h > h_4 \\ 1 & h_2 \geq h \geq h_3 \\ \frac{h - h_1}{h_2 - h_1} & h_1 > h > h_2 \\ 0 & h \leq h_4 \text{ or } h \geq h_1 \end{cases} \quad (\text{B.5})$$

472 Parameterized by four critical values of pressure head, Eq. (B.5) defines maximal uptake ($\alpha = 1$)
473 when the soil water pressure head is $h_2 \geq h \geq h_3$. Water uptake decreases linearly above or below
474 that range ($h_3 > h > h_4$ or $h_1 > h > h_2$). And uptake is zero when $h \leq h_4$ or $h \geq h_1$. According
475 to the Hydrus-1D database, the parameter values for maize are $h_1 = -1.5$, $h_2 = -3.0$, $h_3 = -60$. and
476 $h_4 = -800$. kPa, respectively. The value of h_3 was allowed to vary as a function of evaporative
477 demand as modeled by Hydrus-1D.

478 Three observation nodes were inserted in the domain at the same depths as the soil moisture
479 sensors, 15, 35 and 50 cm. Soil moisture values simulated at the observation nodes were used to
480 determine the simulated available water (*SAW*), using the same procedure as with the field data.
481 The potential evaporation and transpiration rates were calculated by partitioning ET_c into potential
482 evaporation (E_p) and transpiration (T_p) based on the canopy cover fraction (α) according to Raes
483 et al. (2009). An atmospheric boundary condition was imposed at the surface and a free drainage
484 condition was used at the bottom. Simulated actual transpiration (ST_a) and simulated applied

485 irrigation (*SAI*) results from each station were extracted. ST_a and *SAI* were calculated by averaging
486 stations located with the dynamic MZs.

487

488 **Appendix C. Irrigation Scheduling**

489 Irrigation scheduling was optimized using the methodology developed by Fontanet (2019).
490 All soil, environmental and crop inputs are the same as described previously for the Hydrus-1D
491 simulations (Appendix B). Possible values for the irrigation scheduling parameters were
492 constrained to be $h_{th} \in \{-10, -20, \dots, -100 \text{ kPa}\}$ and $\tau \in \{1, 2, 3, 4 \text{ h}\cdot\text{d}^{-1}\}$. The irrigation rate
493 was constant ($6.5 \text{ l}\cdot\text{h}^{-1}\cdot\text{m}^{-2}$). The soil depth used to trigger irrigation (Z_{tr}) changed during the
494 growing season, becoming deeper as the season progressed. Irrigation parameters have been
495 defined at each station and at different crop growing stages (V0-V5, V6-V10, V11-V15, VT, R1-
496 R6). The optimal irrigation at each grow stage and MZ are the average values obtained for the
497 stations located in the MZ.

498

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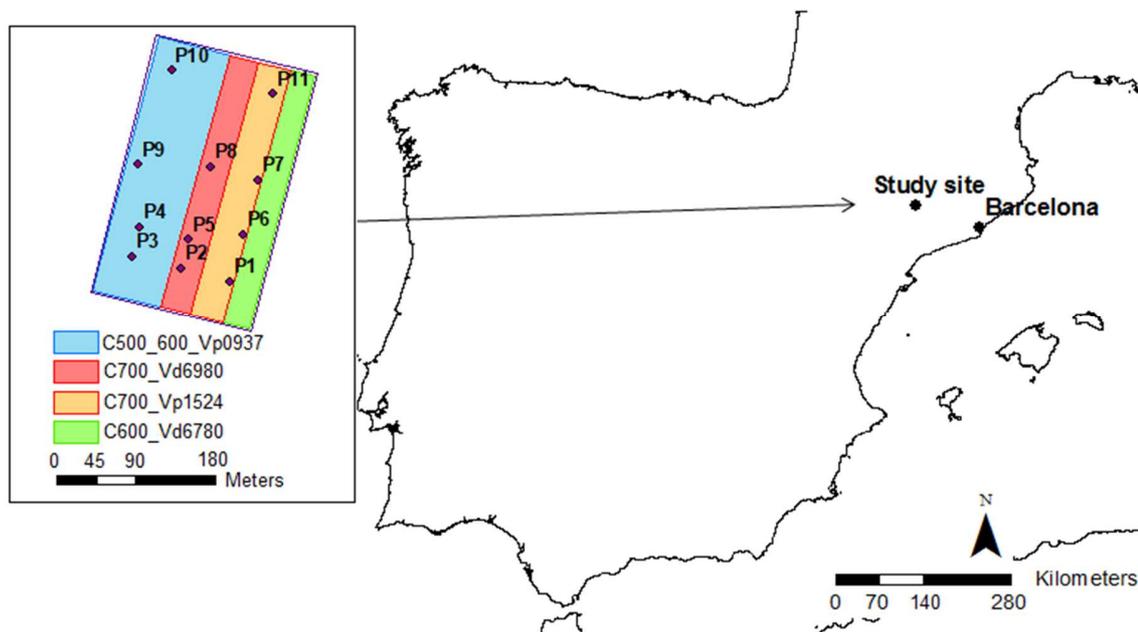
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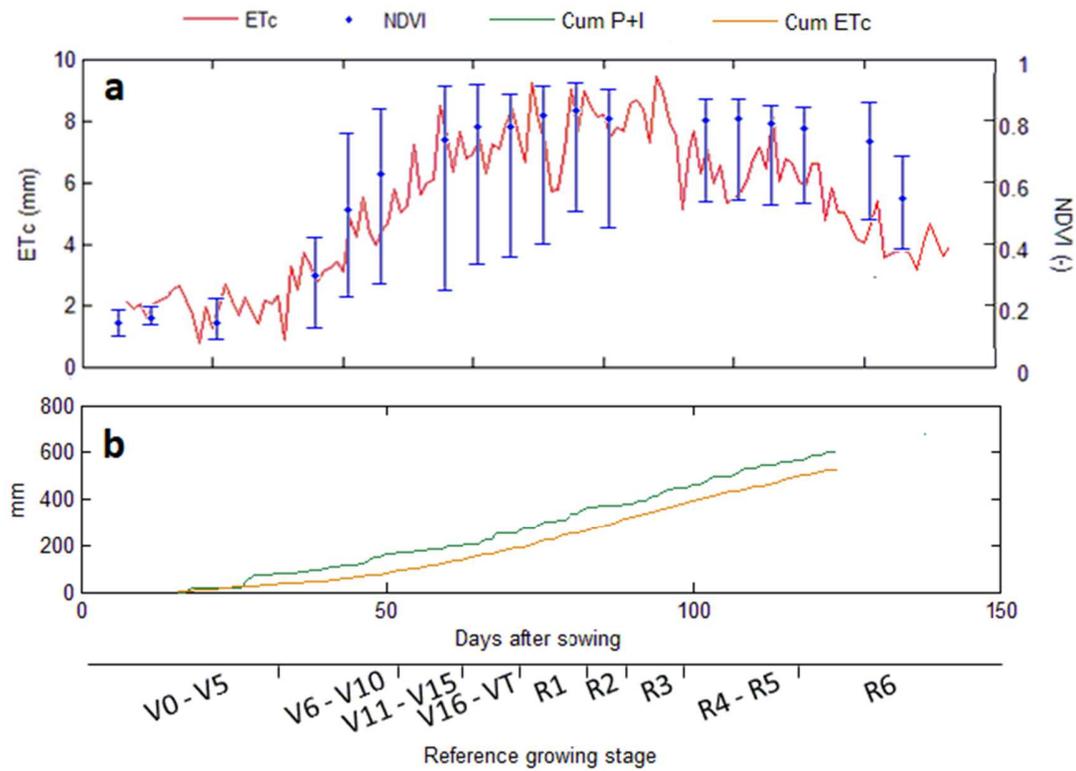
685 **Figures:**



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687 Figure 1. Study site location, soil moisture station locations, and maize variety plantings. The
688 blue area represents maize variety p0937 (a combination of 500 and 600 series), the red area is
689 variety d6980 (700 series), the yellow area is p1524 (700 series), and the green area is d6780
690 (600 series).

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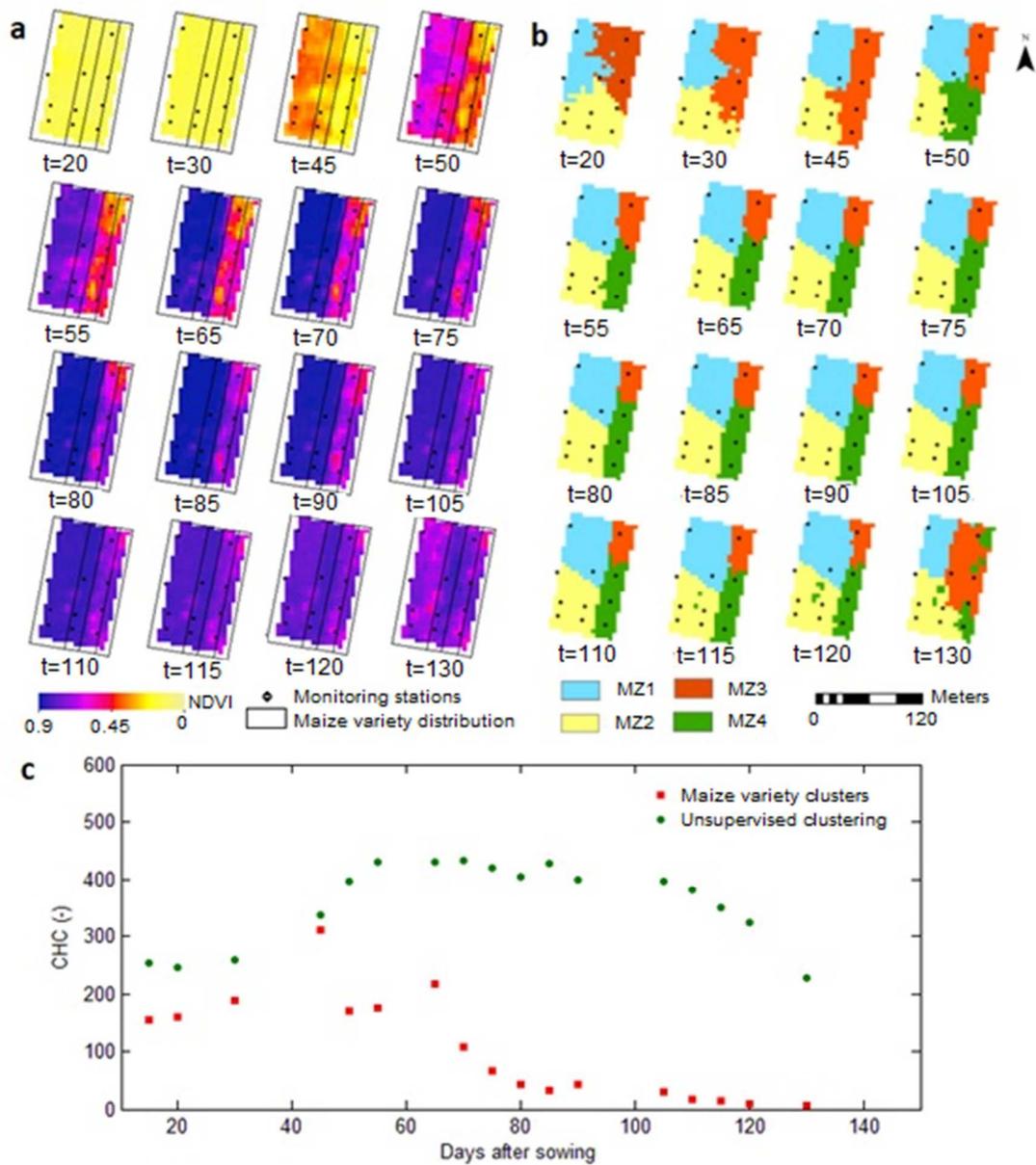


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693 Figure 2. Field average evapotranspiration, NDVI, and cumulative water fluxes as a function
 694 of time and maize growth stage. The bars on the NDVI data indicate field maximum and
 695 minimum values. (V is vegetative stage; R is reproductive stage NDVI is Normalized Difference
 696 Vegetation Index; ETc is daily water requirements; Cum P+I is cumulative Precipitation and
 697 Irrigation; and Cum ETc is cumulative water requirements).

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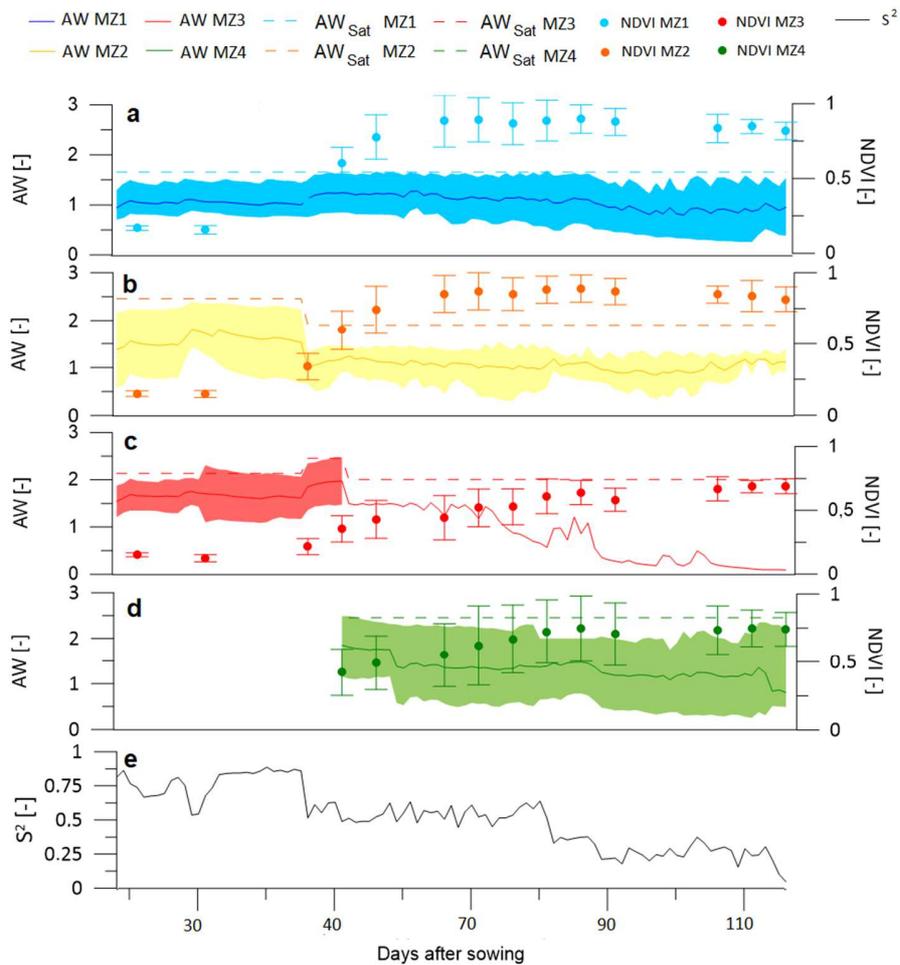
701 Figure 3. a) Normalized Difference Vegetation Index (NDVI) datasets measured by Sentinel

702 2 satellite through the growing season; b) dynamic management zone (MZ) delineation. The

703 letter t indicates days after sowing; and c) Calinski-Harabaz criterion (CHC) for the NDVI

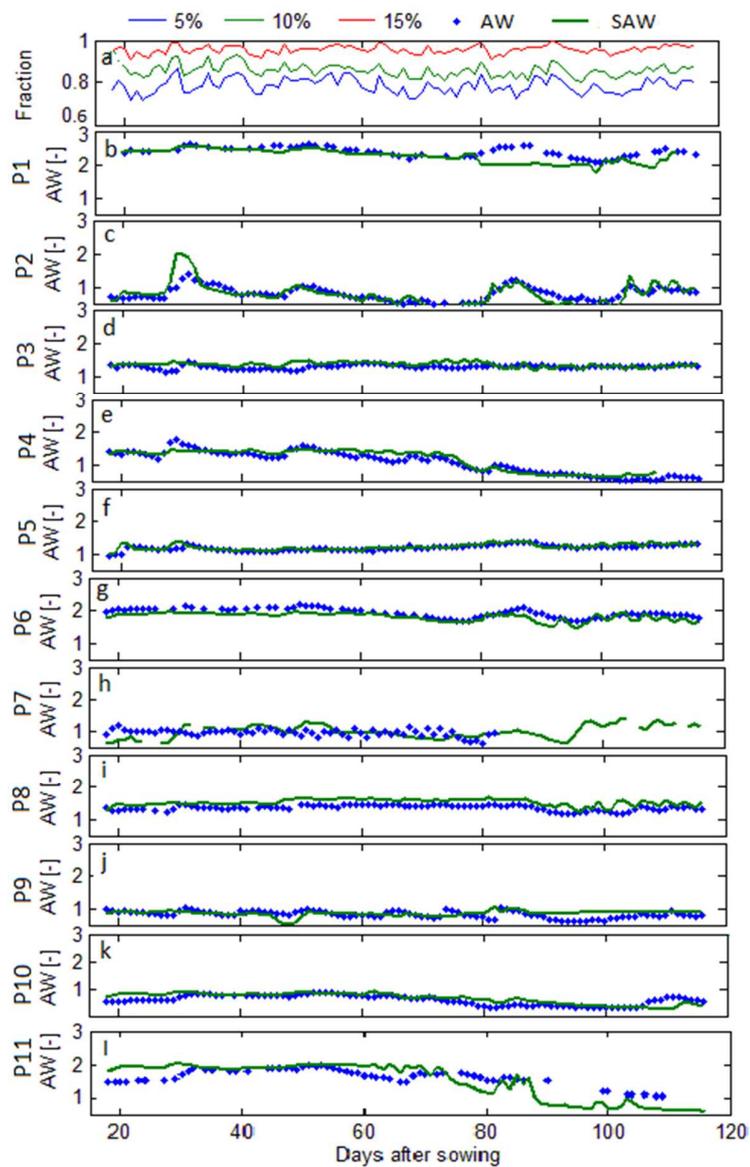
704 grouped by maize variety (red squares) and with the unsupervised fuzzy-k clustering (green

705 dots).



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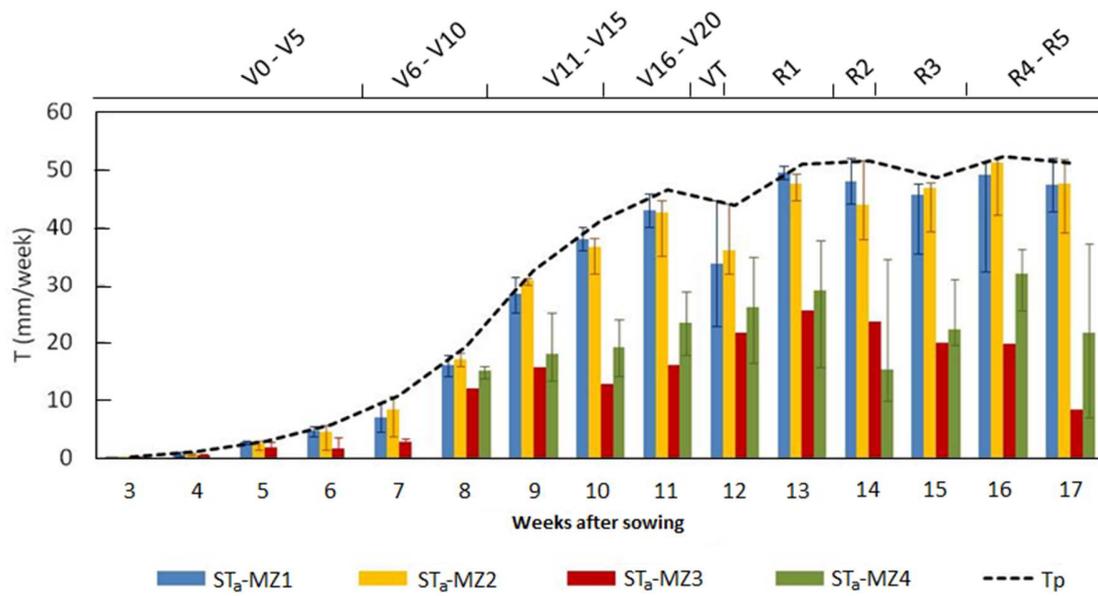
Figure 4. Soil profile available water (AW) and NDVI averages for a) MZ1, b) MZ2, c) MZ3, d) MZ4. Shaded areas represent the maximum in minimum AW at each MZ, while dash lines show available water saturated (AW_{sat}) (θ) and field capacity point (θ_{fc}). Error bars represents the maximum and minimum NDVI at each MZ. Note that $AW = 1$ corresponds to a soil water content equal to field capacity. Panel e) shows the daily total within-MZ weighted variance (S^2) of AW relative to the daily field-wide AW variance (i.e., $S^2=1$).



715

716 Figure 5. a) Evaluation of profile available water (AW) simulations showing the fraction of
 717 error greater than 5, 10, and 15%. b to l) Comparison between measured available water (AW)
 718 and simulated available water (SAW) at each station (P1 - P11).

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Figure 6. Simulated weekly transpiration at each MZ with the growing stages. Error bars represent the maximum and minimum and the dash line shows the weekly potential transpiration.

724 **Tables**725 Table 1. Soil samples texture, Organic Matter (OM) and bulk density (ρ_b) averages at each station.

Station	Depth (cm)	D<0.002 mm Clay (%)	0.002<D<0.02 mm Fine Silt (%)	0.02<D<0.05 mm Coarse Silt (%)	0.05<D<2 mm Sand (%)	OM (%)	ρ_b (gr/cm ³)
P1	0 - 5	36	27.3	13.8	22.9	1.18	1.66
	5 - 35	32	33.6	14.5	19.9	0.71	1.63
	35 - 60	26.5	28.1	9.7	35.7	0.5	1.68
P2	0 - 5	25.9	26.4	14.8	32.9	1.59	1.57
	5 - 35	25.2	26.1	15.1	33.6	1.1	1.58
	35 - 60	24.2	23.4	14.7	37.7	0.98	1.59
P3	0 - 5	36.5	32.1	14.5	16.9	0.7	1.54
	5 - 35	21.3	27.8	16.7	34.2	0.5	1.65
	35 - 60	24.4	31.8	8.3	35.9	0.65	1.60
P4	0 - 5	28.7	23.6	13.2	34.5	2.71	1.48
	5 - 35	28.5	28.9	11	31.6	1.02	1.59
	35 - 60	28.6	19.8	10.4	41.2	1.14	1.60
P5	0 - 5	22.5	26.3	15.6	35.6	0.57	1.56
	5 - 35	28.9	36.6	20.3	14.2	0.72	1.58
	35 - 60	21.8	28.9	7.3	42.0	0.42	1.56
P6	0 - 5	29.9	26.9	15.1	28.1	2.11	1.64
	5 - 35	29.3	25.7	14.9	30.1	0.85	1.67
	35 - 60	30.2	26	14.8	29.0	0.7	1.69
P7	0 - 5	28.1	36	17.1	18.8	3.14	1.65
	5 - 35	28	27.8	11.9	32.3	1.48	1.72
	35 - 60	27.2	24.3	14.3	34.2	1.27	1.69
P8	0 - 5	25.7	28.7	15.2	30.4	2.22	1.58
	5 - 35	27.7	26.1	14.7	31.5	1.5	1.64
	35 - 60	29.2	27.3	14.7	28.8	1.02	1.78
P9	0 - 5	23.7	26.1	14.8	35.4	2.48	1.53
	5 - 35	23.6	27.8	14.4	34.2	1.06	1.51
	35 - 60	23.5	27.7	14.8	34	0.99	1.51
P10	0 - 5	27.7	25.8	20.3	26.2	1.84	1.61
	5 - 35	28.3	29.5	19.2	26.0	0.72	1.62
	35 - 60	24.6	33.5	9.5	32.4	0.81	1.80
P11	0 - 5	29.4	35.9	14.9	19.8	0.73	1.63
	5 - 35	30.3	34.7	14.9	20.1	0.5	1.65
	35 - 60	26.1	30.5	16.4	27.0	0.5	1.64

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727

728 Table 2. Soil hydraulic parameters from each station, where: θ_s is the saturated water content; θ_r is the residual water
 729 content; α and n are shape parameters; K_s is the saturated hydraulic conductivity; θ_{fc} is simulated field capacity; and
 730 θ_{wp} is wilting point. θ_s , θ_r and K_s parameters are fixed, while, α , n parameters are fitted.

Station	Depth (cm)	θ_s ($\text{cm}^3 \cdot \text{cm}^{-3}$)	θ_r ($\text{cm}^3 \cdot \text{cm}^{-3}$)	α (cm^{-1})	n (-)	K_s ($\text{cm} \cdot \text{d}^{-1}$)	θ_{fc} ($\text{cm}^3 \cdot \text{cm}^{-3}$)	θ_{wp} ($\text{cm}^3 \cdot \text{cm}^{-3}$)
P1	0 - 5	0.424	0.026	0.0169	1.140	2.05	0.345	0.196
	5 - 35	0.407	0.027	0.0150	1.141	2.52	0.351	0.190
	35 - 60	0.364	0.037	0.0115	1.232	1.00	0.350	0.110
P2	0 - 5	0.389	0.061	0.0126	1.364	2.95	0.270	0.103
	5 - 35	0.388	0.060	0.0130	1.358	2.94	0.265	0.104
	35 - 60	0.321	0.047	0.0242	1.354	1.53	0.290	0.124
P3	0 - 5	0.418	0.012	0.0103	1.313	4.42	0.330	0.085
	5 - 35	0.362	0.025	0.0101	1.329	5.63	0.273	0.070
	35 - 60	0.341	0.017	0.0083	1.345	11.47	0.261	0.066
P4	0 - 5	0.439	0.024	0.0658	1.301	5.70	0.340	0.187
	5 - 35	0.400	0.031	0.0143	1.290	4.60	0.300	0.192
	35 - 60	0.395	0.018	0.0424	1.315	4.90	0.315	0.181
P5	0 - 5	0.450	0.062	0.0099	1.497	6.88	0.340	0.070
	5 - 35	0.460	0.067	0.0094	1.402	1.94	0.340	0.080
	35 - 60	-	-	-	-	-	-	-
P6	0 - 5	0.420	0.030	0.0126	1.153	12.00	0.371	0.172
	5 - 35	0.430	0.050	0.0828	1.154	9.40	0.390	0.198
	35 - 60	0.421	0.010	0.0974	1.146	8.10	0.390	0.182
P7	0 - 5	0.375	0.024	0.0105	1.118	1.06	0.300	0.208
	5 - 35	0.349	0.026	0.0380	1.141	3.34	0.300	0.196
	35 - 60	0.361	0.049	0.0391	1.141	4.10	0.280	0.107
P8	0 - 5	0.402	0.040	0.0135	1.375	4.01	0.310	0.123
	5 - 35	0.379	0.030	0.0115	1.356	3.05	0.280	0.090
	35 - 60	0.328	0.020	0.0121	1.287	1.75	0.280	0.080
P9	0 - 5	0.420	0.060	0.0105	1.462	5.79	0.300	0.089
	5 - 35	0.430	0.060	0.0107	1.441	4.70	0.330	0.091
	35 - 60	0.430	0.060	0.0109	1.433	5.52	0.330	0.090
P10	0 - 5	0.389	0.073	0.0115	1.421	3.98	0.301	0.105
	5 - 35	0.387	0.072	0.0112	1.425	4.56	0.300	0.080
	35 - 60	0.320	0.058	0.0181	1.256	1.87	0.290	0.090
P11	0 - 5	0.400	0.012	0.0784	1.121	10.00	0.380	0.188
	5 - 35	0.451	0.018	0.0308	1.141	5.27	0.375	0.188
	35 - 60	0.420	0.014	0.0121	1.112	11.00	0.350	0.250

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732

733 Table 3. Periods where one or more stations change MZ membership.

Period (Day after sowing)	MZ1	MZ2	MZ3	MZ4
Period 1 (19-29)	P8, P9, P10	P1, P2, P3, P4, P5, P6	P7, P11	-
Period 2 (30-44)	P8, P9, P10	P1, P2, P3, P4, P5	P6, P7, P11	-
Period 3 (45-49)	P8, P10	P2, P3, P4, P5, P9	P1, P6, P7, P11	-
Period 4 (50-54)	P8, P10	P2, P3, P4, P9	P7, P11	P1, P5, P6
Period 5 (55-115)	P8, P10	P2, P3, P4, P5, P9	P11	P1, P6, P7

734

735 Table 4. Irrigation scheduling calendar based on growing stages and MZs distribution. h_{th} , is the possible pressure head threshold (the optimal pressure head
736 threshold in bold); I , is the irrigation required to achieve maximized transpiration; τ , is the irrigation duration; Z_{tr} , is the trigger soil depth. Optimal irrigation
737 parameters representing the optimal irrigation strategy is represented in bold.

	V0-V5		V6-V10		V11-V15		VT		R1-R6		
	Trigger Depth = 10 cm		Trigger Depth = 20cm		Trigger Depth = 20 cm		Trigger Depth = 40 cm		Trigger Depth = 40 cm		
	h_{th} (kPa)	Irrig. Required (mm)	τ (h)	Irrig. Required (mm)	τ (h)	Irrig. Required (mm)	τ (h)	Irrig. Required (mm)	τ (h)	Irrig. Required (mm)	τ (h)
MZ1	0	-	-	-	-	-	-	-	-	-	-
	-10	-	-	-	-	-	-	-	-	-	-
	-20	-	-	-	-	-	-	-	-	-	-
	-23.3	-	-	12.5	1.9	-	-	-	-	-	-
	-26.7	13.1	2.0	13.5	2.1	-	-	-	-	-	-
	-30	14.0	2.2	14.1	2.2	19.0	2.9	15.0	2.3	17.0	2.6
	-40	15.0	2.3	14.5	2.2	21.0	3.2	17.0	2.6	21.0	3.2
	-60	16.0	2.5	18.5	2.8	25.0	3.8	23.0	3.5	29.0	4.5
	-100	17.1	2.6	22.5	3.5	29.0	4.5	33.0	5.1	45.0	6.9
MZ2	0	-	-	-	-	-	-	-	-	-	-
	-10	-	-	-	-	-	-	-	-	-	-
	-18.3	12.4	1.9	-	-	-	-	-	-	-	-
	-20	12.4	1.9	-	-	-	-	-	-	-	-
	-24	12.9	2.0	15.3	2.4	-	-	-	-	-	-
	-30	13.9	2.1	18.3	2.8	13.0	2.0	13.0	2.0	13.0	2.0
	-40	14.4	2.2	19.3	3.0	18.0	2.8	23.0	3.5	23.0	3.5
	-60	16.9	2.6	24.3	3.7	23.0	3.5	33.0	5.1	33.0	5.1
	-100	19.9	3.1	30.3	4.7	29.0	4.5	45.0	6.9	45.0	6.9

	h_{th} (kPa)	Irrig. Required (mm)	τ (h)								
MZ3	0	-	-	-	-	-	-	-	-	-	-
	-10	-	-	13.0	2.0	13.0	2.0	13.0	2.0	13.0	2.0
	-20	13.0	2.0	17.0	2.6	17.0	2.6	21.0	3.2	21.0	3.2
	-30	15.0	2.3	21.0	3.2	21.0	3.2	29.0	4.5	29.0	4.5
	-40	16.0	2.5	23.0	3.5	23.0	3.5	33.0	5.1	33.0	5.1
	-60	18.0	2.8	27.0	4.2	27.0	4.2	41.0	6.3	41.0	6.3
	-100	20.5	3.2	28.0	4.3	28.0	4.3	43.0	6.6	43.0	6.6

	h_{th} (kPa)	Irrig. Required (mm)	τ (h)								
MZ4	0	-	-	-	-	-	-	-	-	-	-
	-10	-	-	-	-	-	-	13.0	2.0	13.0	2.0
	-16.7	-	-	-	-	15.0	2.3	15.0	2.3	15.0	2.3
	-20	-	-	-	-	16.0	2.5	17.0	2.6	17.0	2.6
	-30	-	-	-	-	19.0	2.9	25.0	3.8	25.0	3.8
	-40	-	-	-	-	21.0	3.2	29.0	4.5	29.0	4.5
	-60	-	-	-	-	23.0	3.5	33.0	5.1	33.0	5.1
-100	-	-	-	-	29.0	4.5	45.0	6.9	45.0	6.9	

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739 Table 5. Comparisons of optimal actual transpiration (OpT_a), optimal water applied ($OpIA$), simulated actual
 740 transpiration (ST_a), and simulated water applied (SAI).

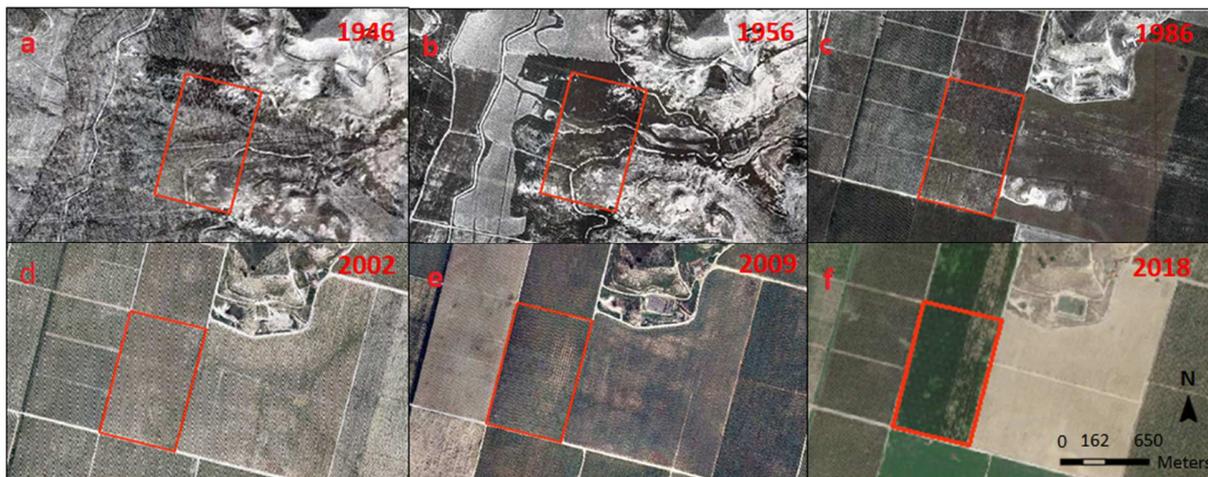
	OpT_a (mm)	$(OpT_a - ST_a)/ST_a$ (%)	$OpIA$ (mm)	$(OpIA - SAI)/SAI$ (%)
MZ1	405.6	8.0	525.5	-11.0
MZ2	405.6	4.8	517.8	-12.8
MZ3	107.5	23.9	217.5	-28.5
MZ4	271.7	52.6	350.2	-16.6

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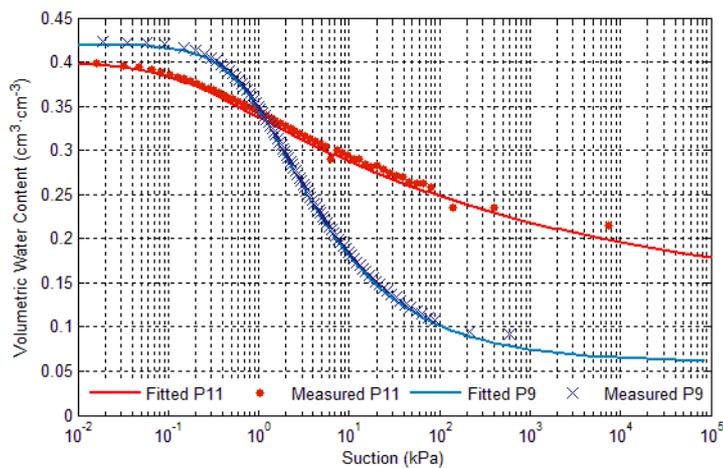
743 **Appendix A. Supplementary data**

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745

746 Figure A.1. Historical land use and topography modifications at the study site.



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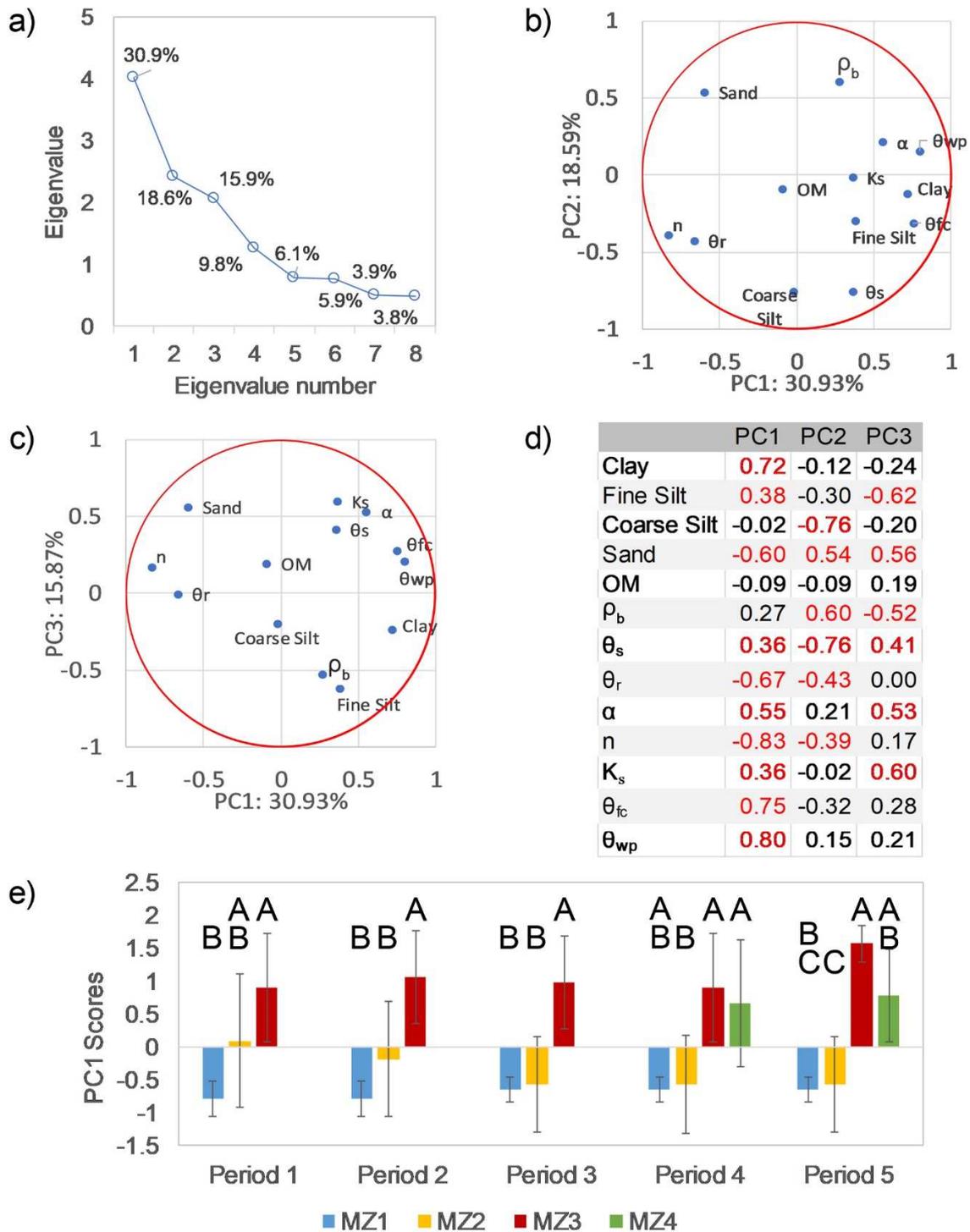
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749 Figure A.2. Soil water retention curves at 10 cm depth from two stations located on opposite

750 edges of the field. Station P9 is located on the west side and P11 on the east.

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754 Figure A.3. a) Eigenvalue and percent of variance explained by the first eight components of the
 755 principal component (PC) analysis; b) bi-plot of select soil properties (clay, fine silt, coarse silt,

756 sand, and organic matter (OM) content; bulk density (ρ_b); water content at saturation (θ_s);
757 residual water content (θ_r); water content at field capacity (θ_{fc}); water content at wilting point
758 (θ_{wp}); saturated hydraulic conductivity (K_s); and shape parameters α and n) for PC1 and PC2; c)
759 same for PC1 and PC3; d) Pearson correlation matrix for the first three PCs and selected soil
760 properties (significant ($p < 0.05$) correlations highlighted in red); and e) averages (bars) and
761 standard deviations (lines) of PC1 for the four management zones (MZs) through the growing
762 season. Capital letters indicate significant ($p < 0.05$) differences within MZs according to the
763 Kruskal-Wallis test.

764